

SECTION: SUBSTATION AUTOMATION SYSTEM

1.0 GENERAL

1.1. The substation automation system shall be offered from a manufacturer who must have designed, manufactured, tested, installed and commissioned substation automation system which must be in satisfactory operation on 220kV system or higher for at least 2 (Two) years as on the date of bid opening.

1.2. The Substation Automation System (SAS) shall be installed to control and monitor all the sub-station equipment from remote control centre (RCC) as well as from local control centre.

The SAS shall contain the following main functional parts:

- Bay control Intelligence Electronic Devices (IED s) for control and monitoring.
- Station Human Machine Interface (HMI)
- Redundant managed switched Ethernet Local Area Network communication infrastructure with hot standby.
- Gateway for remote control via industrial grade hardware (to RCC) through IEC60870-5-101 protocol.
- Gateway for remote supervisory control (to RSCC), the gateway should be able to communicate with RSCC on IEC 60870-5-101 protocol. The specific protocol to be implemented is enclosed as Appendix-I. For Northern Region –I & II, Eastern Region I & II and North Eastern Region interoperability profile shall be as per AREVA inter operability profile and for other regions it shall be as per GE's interoperability profile. . It shall be the bidder's responsibility to integrate his offered system with existing RSCC system for exchange of desired data. The requirement of IO point shall be worked out by the bidder as per criterion enclosed as Appendix-II for data exchange with RLDCs.
- Remote HMI.
- Peripheral equipment like printers, display units, key boards, Mouse etc.

1.3. It shall enable local station control via a PC by means of human machine interface (HMI) and control software package, which shall contain an extensive range of supervisory control and data acquisition (SCADA) functions.

1.4. It shall include communication gateway, intelligent electronic devices (IED) for bay control and inter IED communication infrastructure. An architecture drawing for SAS is enclosed.

1.5. The communication gateway shall facilitate the information flow with remote control centres. The bay level intelligent electronic devices (IED) for protection and control shall provide the direct connection to the

switchgear without the need of interposing components and perform control, protection, and monitoring functions.

2. **System design**

2.1 **General system design**

The Substation Automation System (SAS) shall be suitable for operation and monitoring of the complete substation including future extensions as given in Section-Project.

The systems shall be of the state-of-the art suitable for operation under electrical environment present in Extra high voltage substations, follow the latest engineering practice, ensure long-term compatibility requirements and continuity of equipment supply and the safety of the operating staff.

The offered SAS shall support remote control and monitoring from Remote Control centres via gateways.

The system shall be designed such that personnel without any background knowledge in Microprocessor-based technology are able to operate the system. The operator interface shall be intuitive such that operating personnel shall be able to operate the system easily after having received some basic training.

The system shall incorporate the control, monitoring and protection functions specified, self-monitoring, signalling and testing facilities, measuring as well as memory functions, event recording and evaluation of disturbance records.

Maintenance, modification or extension of components may not cause a shutdown of the whole substation automation system. Self-monitoring of components, modules and communication shall be incorporated to increase the availability and the reliability of the equipment and minimize maintenance.

Bidder shall offer the Bay level unit (a bay comprises of one circuit breaker and associated disconnecter, earth switches and instrument transformer), bay mimic along with relay and protection panels and PLCC panels (described in other sections of technical specifications) housed in air-conditioned *Switchyard Panel Room* suitably located in switchyard and Station HMI in Control Room building for overall optimisation in respect of cabling and control room building..

2.2 **System architecture**

The SAS shall be based on a decentralized architecture and on a concept of bay-oriented, distributed intelligence.

Functions shall be decentralized, object-oriented and located as close as possible to the process.

The main process information of the station shall be stored in distributed databases. The typical SAS architecture shall be structured in two levels, i.e. in a station and a bay level.

At bay level, the IEDs shall provide all bay level functions regarding control, monitoring and protection, inputs for status indication and outputs for commands. The IEDs should be directly connected to the switchgear without any need for additional interposition or transducers.

Each bay control IED shall be independent from each other and its functioning shall not be affected by any fault occurring in any of the other bay control units of the station.

The data exchange between the electronic devices on bay and station level shall take place via the communication infrastructure. This shall be realized using fibre-optic cables, thereby guaranteeing disturbance free communication. The fibre optic cables shall be run in G . I conduit pipes. Data exchange is to be realised using IEC 61850 protocol with a redundant managed switched Ethernet communication infrastructure

The communication shall be made in fault tolerant ring in redundant mode, excluding the links between individual bay IEDs to switch wherein the redundant connections are not envisaged, such that failure of one set of fiber shall not affect the normal operation of the SAS. However failure of fiber shall be alarmed in SAS. Each fiber optic cable shall have four (4) spare fibers

At station level, the entire station shall be controlled and supervised from the station HMI. It shall also be possible to control and monitor the bay from the bay level equipment at all times.

Clear control priorities shall prevent operation of a single switch at the same time from more than one of the various control levels, i.e. RCC, station HMI, bay level or apparatus level. The priority shall always be on the lowest enabled control level.

The station level contains the station-oriented functions, which cannot be realised at bay level, e.g. alarm list or event list related to the entire substation, gateway for the communication with remote control centres.

The GPS time synchronising signal (as specified in the section relay & protection) for the synchronization of the entire system shall be provided.

The SAS shall contain the functional parts as described in para 1.2 above.

2.3 FUNCTIONAL REQUIREMENTS

The high-voltage apparatus within the station shall be operated from different places:

- Remote control centres
- Station HMI.
- Local Bay controller IED (in the bays)

Operation shall be possible by only one operator at a time.

The operation shall depend on the conditions of other functions, such as interlocking, synchrocheck, etc. (see description in "Bay level control functions").

2.3.1 Select-before-execute

For security reasons the command is always to be given in two stages: selection of the object and command for operation under all mode of operation except emergency operation. Final execution shall take place only when selection and command are actuated.

2.3.2 Command supervision

Bay/station interlocking and blocking

Software Interlocking is to be provided to ensure that inadvertent incorrect operation of switchgear causing damage and accidents in case of false operation does not take place.

In addition to software interlocking hardwired interlocking are to be provided for:

- (a) Bus Earth switch Interlocking
- (b) Transfer Bus interlocking (if applicable)

It shall be a simple layout, easy to test and simple to handle when upgrading the station with future bays. For software interlocking the bidder shall describe the scenario while an IED of another bay is switched off or fails.

A software interlock override function shall be provided which can be enabled to bypass the interlocking function.

2.3.3 Run Time Command cancellation

Command execution timer (configurable) must be available for each control level connection. If the control action is not completed within a specified time, the command should get cancelled.

2.3.4 Self-supervision

Continuous self-supervision function with self-diagnostic feature shall be included.

2.3.5 User configuration

The monitoring, controlling and configuration of all input and output logical signals and binary inputs and relay outputs for all built-in functions and signals shall be possible both locally and remotely.

It shall also be possible to interconnect and derive input and output signals, logic functions, using built-in functions, complex voltage and currents, additional logics (AND-gates, OR gates and timers). (Multi-activation of these additional functions should be possible).

The Functional requirement shall be divided into following levels:

- a. Bay (a bay comprises of one circuit breaker and associated disconnecter, earth switches and instrument transformer) Level Functions
- b. System Level Functions

3.1. Bay level functions

In a decentralized architecture the functionality shall be as close to the process as possible. In this respect, the following functions can be allocated at bay level:

- Bay control functions including data collection functionality in bay control/protection unit.
- Bay protection functions

Separate IEDs shall be provided for bay control function and bay protection function.

3.1.1. Bay control functions

3.1.1.1. Overview

Functions

- Control mode selection
- Select-before-execute principle
- Command supervision:
 - Interlocking and blocking
 - Double command
- Synchrocheck, voltage selection
- Run Time Command cancellation
- Transformer tap changer control (Raise and lower of tap) (for power transformer bays)
- Operation counters for circuit breakers and pumps
- Hydraulic pump/ Air compressor runtime supervision
- Operating pressure supervision through digital contacts only
- Breaker position indication per phase
- Alarm annunciation
- Measurement display
- Local HMI (local guided, emergency mode)
- Interface to the station HMI.
- Data storage for at least 200 events
- Extension possibilities with additional I/O's inside the unit or via fibre-optic communication and process bus

3.1.1.2. Control mode selection

Bay level Operation:

As soon as the operator receives the operation access at bay level the operation is normally performed via bay control IED. During normal

operation bay control unit allows the safe operation of all switching devices via the bay control IED.

EMERGENCY Operation

It shall be possible to close or open the selected Circuit Breaker with ON or OFF push buttons even during the outage of bay IED.

REMOTE mode

Control authority in this mode is given to a higher level (Remote Control Centre) and the installation can be controlled only remotely. Control operation from lower levels shall not be possible in this operating mode.

3.1.1.3. Synchronism and energizing check

The synchronism and energizing check functions shall be bay-oriented and distributed to the bay control and/or protection devices. These features are:

- Settable voltage, phase angle, and frequency difference.
- Energizing for dead line - live bus, live line - dead bus or dead line – dead bus with no synchro-check function.
- Synchronising between live line and live bus with synchro-check function

Voltage selection

The voltages relevant for the Synchro check functions are dependent on the station topology, i.e. on the positions of the circuit breakers and/or the isolators. The correct voltage for synchronizing and energizing is derived from the auxiliary switches of the circuit breakers, the isolator, and earthing switch and shall be selected automatically by the bay control and protection IEDs.

3.1.1.4. Transformer tap changer control

Raise and lower operation of OLTC taps of transformer shall be facilitated through Bay controller IED.

3.1.2. Bay protection functions0

3.1.2.1. General

The protection functions are independent of bay control function. The protection shall be provided by separate protection IEDs (numerical relays) and other protection devices as per section Relay & Protection.

IEDs, shall be connected to the communication infrastructure for data sharing and meet the real-time communication requirements for automatic functions. The data presentation and the configuration of the various IEDs shall be compatible with the overall system communication and data exchange requirements.

Event and disturbance recording function

Each IED should contain an event recorder capable of storing at least 200 time-tagged events. The disturbance recorder function shall be as per detailed in section C&R

3.1.2.2. Bay Monitoring Function:

Analogue inputs for voltage and current measurements shall be connected directly to the voltage transformers (VT) and the current transformers (CT) without intermediate transducers. The values of active power (W), reactive power (VAR), frequency (Hz), and the rms values for voltage (U) and current (I) shall be calculated in the Bay control/protection unit.

3.2. System level functions

3.2.1. Status supervision

The position of each switchgear, e.g. circuit breaker, isolator, earthing switch, transformer tap changer etc., shall be supervised continuously. Every detected change of position shall be immediately displayed in the single-line diagram on the station HMI screen, recorded in the event list, and a hard copy printout shall be produced. Alarms shall be initiated in the case of spontaneous position changes.

The switchgear positions shall be indicated by two auxiliary switches, normally closed (NC) and normally open (NO), which shall give ambivalent signals. An alarm shall be initiated if these position indications are inconsistent or if the time required for operating mechanism to change position exceeds a predefined limit.

The SAS shall also monitor the status of sub-station auxiliaries. The status and control of auxiliaries shall be done through separate one or more IED and all alarm and analogue values shall be monitored and recoded through this IED.

3.2.2. Measurements

The analogue values acquired/calculated in bay control/protection unit shall be displayed locally on the station HMI and in the control centre. The abnormal values must be discarded. The analogue values shall be updated every 2 seconds.

Threshold limit values shall be selectable for alarm indications.

3.2.3. Event and alarm handling

Events and alarms are generated either by the switchgear, by the control IEDs, or by the station level unit. They shall be recorded in an event list in the station HMI. Alarms shall be recorded in a separate alarm list and appear on the screen. All, or a freely selectable group of events and alarms shall also be printed out on an event printer. The alarms and events shall be time-tagged with a time resolution of 1 ms. The tentative list for various feeders and systems are enclosed as Annexure-I

3.2.4. Station HMI

3.2.4.1. Substation HMI Operation:

On the HMI the object has to be selected first. In case of a blocking or interlocking conditions are not met, the selection shall not be possible and an appropriate alarm annunciation shall occur. If a selection is valid the position indication will show the possible direction, and the appropriate control execution button shall be pressed in order to close or open the corresponding object.

Control operation from other places (e.g. REMOTE) shall not be possible in this operating mode.

3.2.4.2. Presentation and dialogues

General

The operator station HMI shall be a redundant with hot standby and shall provide basic functions for supervision and control of the substation. The operator shall give commands to the switchgear on the screen via mouse clicks.

The HMI shall give the operator access to alarms and events displayed on the screen. Aside from these lists on the screen, there shall be a printout of alarms or events in an event log.

An acoustic alarm shall indicate abnormalities, and all unacknowledged alarms shall be accessible from any screen selected by the operator.

The following standard pictures shall be available from the HMI:

- Single-line diagram showing the switchgear status and measured values
- Control dialogues with interlocking or blocking information details. This control dialogue shall tell the operator whether the device operation is permitted or blocked.
- Measurement dialogues
- Alarm list, station / bay-oriented
- Event list, station / bay-oriented
- System status

3.2.4.3. HMI design principles

Consistent design principles shall be adopted with the HMI concerning labels, colours, dialogues and fonts. Non-valid selections shall be dimmed out.

The object status shall be indicated using different status colours for:

- Selected object under command
- Selected on the screen
- Not updated, obsolete values, not in use or not sampled
- Alarm or faulty state
- Warning or blocked

- Update blocked or manually updated
- Control blocked
- Normal state

3.2.4.4. Process status displays and command procedures

The process status of the substation in terms of actual values of currents, voltages, frequency, active and reactive powers as well as the positions of circuit breakers, isolators and transformer tap-changers shall be displayed in the station single-line diagram.

In order to ensure a high degree of security against undesired operation, a "select-before-execute" command procedure shall be provided. After the "selection" of a switch, the operator shall be able to recognize the selected device on the screen, and all other switchgear shall be blocked. As communication between control centre and device to be controlled is established, the operator shall be prompted to confirm the control action and only then final execute command shall be accepted. After the "execution" of the command the operated switching symbol shall flash until the switch has reached its new position.

The operator shall be in a position to execute a command only, if the switch is not blocked and if no interlocking condition is going to be violated. The interlocking statements shall be checked by the interlocking scheme implemented at bay and station level.

After command execution the operator shall receive a confirmation that the new switching position has been reached or an indication that the switching procedure was unsuccessful with the indication of the reason for non-functioning.

3.2.4.5. System supervision & display

The SAS system shall be comprehensively self-monitored such that faults are immediately indicated to the operator, possibly before they develop into serious situations. Such faults are recorded as a faulty status in a system supervision display. This display shall cover the status of the entire substation including all switchgear, IEDs, communication infrastructure and remote communication links, and printers at the station level, etc.

3.2.4.6. Event list

The event list shall contain events that are important for the control and monitoring of the substation.

The event and associated time (with 1 ms resolution) of its occurrence has to be displayed for each event.

The operator shall be able to call up the chronological event list on the monitor at any time for the whole substation or sections of it.

A printout of each display shall be possible on the hard copy printer.

The events shall be registered in a chronological event list in which the type of event and its time of occurrence are specified. It shall be possible

to store all events in the computer for at least one month. The information shall be obtainable also from a printed event log.

The chronological event list shall contain:

- Position changes of circuit breakers, isolators and earthing devices
- Indication of protective relay operations
- Fault signals from the switchgear
- Indication when analogue measured values exceed upper and lower limits. Suitable provision shall be made in the system to define two level of alarm on either side of the value or which shall be user defined for each measurands.
- Loss of communication.

Filters for selection of a certain type or group of events shall be available. The filters shall be designed to enable viewing of events grouped per:

- Date and time
- Bay
- Device
- Function e.g. trips, protection operations etc.
- Alarm class

3.2.4.7. Alarm list

Faults and errors occurring in the substation shall be listed in an alarm list and shall be immediately transmitted to the control centre. The alarm list shall substitute a conventional alarm tableau, and shall constitute an evaluation of all station alarms. It shall contain unacknowledged alarms and persisting faults. The date and time of occurrence shall be indicated.

The alarm list shall consist of a summary display of the present alarm situation. Each alarm shall be reported on one line that contains:

- The date and time of the alarm
- The name of the alarming object
- A descriptive text
- The acknowledgement state.

Whenever an alarm condition occurs, the alarm condition must be shown on the alarm list and must be displayed in a flashing state along with an audible alarm. After acknowledgement of the alarm, it should appear in a steady (i.e. not flashing) state and the audible alarm shall stop. The alarm should disappear only if the alarm condition has physically cleared and the operator has reset the alarm with a reset command. The state of the alarms shall be shown in the alarm list (Unacknowledged and persistent, Unacknowledged and cleared, Acknowledged and persistent).

Filters for selection of a certain type or group of alarms shall be available as for events.

3.2.4.8. Object picture

When selecting an object such as a circuit breaker or isolator in the single-line diagram, the associated bay picture shall be presented first. In the selected object picture, all attributes like

- Type of blocking
- Authority
- Local / remote control
- RSCC / SAS control
- Errors
- etc.,

shall be displayed.

3.2.4.9. Control dialogues

The operator shall give commands to the system by means of mouse click located on the single-line diagram. Data entry is performed with the keyboard. Dedicated control dialogues for controlling at least the following devices shall be available:

- Breaker and disconnectors
- Transformer tap-changer

3.2.5. User-authority levels

It shall be possible to restrict activation of the process pictures of each object (bays, apparatus...) within a certain user authorisation group. Each user shall then be given access rights to each group of objects, e.g.:

- Display only
- Normal operation (e.g. open/close of switchgear)
- Restricted operation (e.g. by-passed interlocking)
- System administrator

For maintenance and engineering purposes of the station HMI, the following authorisation levels shall be available:

- No engineering allowed
- Engineering/configuration allowed
- Entire system management allowed

The access rights shall be defined by passwords assigned during the log-in procedure. Only the system administrator shall be able to add/remove users and change access rights.

3.2.6. Reports

The reports shall provide time-related follow-ups of measured and calculated values. The data displayed shall comprise:

- Trend reports:
 - Day (mean, peak)
 - Month (mean, peak)
 - Semi-annual (mean, peak)
 - Year (mean, peak)
- Historical reports of selected analogue Values:
 - Day (at 15 minutes interval)
 - Week
 - Month
 - Year

It shall be possible to select displayed values from the database in the process display on-line. Scrolling between e.g. days shall be possible. Unsure values shall be indicated. It shall be possible to select the time period for which the specific data are kept in the memory.

Following printouts shall be available from the printer and shall be printed on demand:

- i. Daily voltage and frequency curves depicting time on X-axis and the appropriate parameters on the Y-axis. The time duration of the curve is 24 hours.
- ii. Weekly trend curves for real and derived analogue values.
- iii. Printouts of the maximum and minimum values and frequency of occurrence and duration of maximum and minimum values for each analogue parameter for each circuit in 24 hr period.
- iv. Provision shall be made for logging information about breaker status like number of operation with date and time indications along with the current value it interrupts (in both condition i.e. manual opening and fault tripping)
- v. Equipment operation details shift wise and during 24 hours.
- vi. Printout on adjustable time period as well as on demand for MW, MVAR, Current, Voltage on each feeder and transformer as well as Tap Positions, temperature and status of pumps and fans for transformers.
- vii. Printout on adjustable time period as well as on demand system frequency and average frequency.
- viii. Reports in specified formats which shall be handed over to successful bidder. The bidder has to develop these reports. The

reports are limited to the formats for which data is available in the SAS database.

3.2.7. Trend display (historical data)

It shall be possible to illustrate all types of process data as trends - input and output data, binary and analogue data. The trends shall be displayed in graphical form as column or curve diagrams with a maximum of 10 trends per screen. Adjustable time span and scaling ranges must be provided.

It shall be possible to change the type of value logging (direct, mean, sum, or difference) on-line in the window. It shall also be possible to change the update intervals on-line in the picture as well as the selection of threshold values for alarming purposes.

3.2.8. Automatic disturbance file transfer

All recorded data from the IEDs with integrated disturbance recorder as well as dedicated disturbance recording systems shall be automatically uploaded (event triggered or once per day) to a dedicated computer and be stored on the hard disc.

3.2.9. Disturbance analysis

The PC-based work station shall have necessary software to evaluate all the required information for proper fault analysis.

3.2.10. IED parameter setting

It shall be possible to access all protection and control IEDs for reading the parameters (settings) from the station HMI or from a dedicated monitoring computer. The setting of parameters or the activation of parameter sets shall only be allowed after entering a password.

3.2.11. Automatic sequences

The available automatic sequences in the system should be listed and described, (e.g. sequences related to the bus transfer). It must be possible to initiate pre-defined automatic sequences by the operator and also define new automatic sequences.

3.3. Gateway

3.3.1 Communication Interface

The Substation Automation System shall have the capability to support simultaneous communications with multiple independent remote master stations,

The Substation Automation System shall have communication ports as follows:

- (a) Two ports for Remote Control Centre
- (b) Two ports for Regional System Coordination Centre (RSCC)

The communication interface to the SAS shall allow scanning and control

of defined points within the substation automation system independently for each control centre. The substation automation system shall simultaneously respond to independent scans and commands from employer's control centres (RCC & RSCC). The substation automation system shall support the use of a different communication data exchange rate (bits per second), scanning cycle, and/or communication protocol to each remote control centre. Also, each control centre's data scan and control commands may be different for different data points within the substation automation system's database.

3.3.2 Remote Control Centre Communication Interface

Employer will supply communication channels between the Substation Automation System and the remote control centre. The communication channels provided by Employer will consist either of power line carrier, microwave, optical fibre, VSAT or leased line , the details of which shall be provided during detailed Engineering .

3.3.3 Interface equipment:

The Contractor shall provide interface equipment for communicating between Substation Automation system and Remote control centre and between Substation Automation system and Regional System Coordination Centre (RSCC). However, the communication channels available for this purpose are specified in section project.

In case of PLCC communication any modem supplied shall not require manual equalization and shall include self-test features such as manual mark/space keying, analogue loop-back, and digital loop-back. The modems shall provide for convenient adjustment of output level and receive sensitivity. The modem should be stand alone complete in all respects including power supply to interface the SAS with communication channel. The configuration of tones and speed shall be programmable and maintained in non-volatile memory in the modem. All necessary hardware and software shall also be in the scope of bidder except the communication link along with communication equipment between substation control room and Remote Control Centre.

3.3.4 Communication Protocol

The communication protocol for gateway to control centre must be open protocol and shall support IEC 60870-5-101 and IEC 61850 for all levels of communication for sub-station automation such as Bay to station HMI, gateway to remote station etc..

4.0 System hardware:

4.1 Redundant Station HMI, Remote HMI and Disturbance Recorder Work station:

The contractor shall provide redundant station HMI in hot standby mode. The servers used in these work stations shall be of industrial grade.

It shall be capable to perform all functions for entire substation including future requirements as indicated in the SLD. It shall use industrial grade components. Processor and RAM shall be selected in such a manner that during normal operation not more than 30% capacity of processing and memory are used. Supplier shall demonstrate these features.

The capacity of hard disk shall be selected such that the following requirement should occupy less than 50% of disk space:

1. Storage of all analogue data (at 15 Minutes interval) and digital data including alarm, event and trend data for thirty(30) days,
2. Storage of all necessary software,
3. 20GB space for OWNER'S use.

Supplier shall demonstrate that the capacity of hard disk is sufficient to meet the above requirement.

4.1.1 **HMI (Human Machine Interface)**

The VDU shall show overview diagrams (Single Line Diagrams) and complete details of the switchgear with a colour display. All event and alarm annunciation shall be selectable in the form of lists. Operation shall be by a user friendly function keyboard and a cursor positioning device. The user interface shall be based on WINDOWS concepts with graphics & facility for panning, scrolling, zooming, decluttering etc.

4.1.2 **Visual Display Units/TFT's (Thin Film Technology)**

The display units shall have high resolution and reflection protected picture screen. High stability of the picture geometry shall be ensured. The screen shall be at least 21" diagonally in size and capable of colour graphic displays.

The display shall accommodate resolution of 1280 X 1024 pixels.

4.1.3 **Printer**

It shall be robust & suitable for operation with a minimum of 132 characters per line. The printing operation shall be quiet with a noise level of less than 45 dB suitable for location in the control room. Printer shall accept and print all ASCII characters via master control computer unit interface.

The printer shall have in built testing facility. Failure of the printer shall be indicated in the Station HMI. The printer shall have an off line mode selector switch to enable safe maintenance. The maintenance should be simple with provisions for ease of change of print head, ribbon changing, paper insertion etc.

All reports and graphics prints shall be printed on laser printer. One dot

matrix printer shall be exclusively used for hourly log printing.

All printers shall be continuously online.

4.1.4 Mass Storage Unit

The mass storage unit shall be built-in to the Station HMI. All operational measured values, and indications shall be stored in a mass-storage unit **in form of DVD RW**. The unit should support at least Read (48X), Write(24X), and Re-Write (10X) operations, with Multi-Session capability. It should support ISO9660, Rockridge and Joliet Filesystems. It should support formatting and use under the operating system provided for Station HMI. The monthly back up of data shall be taken on disc. The facility of back up of data shall be inherent in the software.

4.1.5 Switched Ethernet Communication Infrastructure:

The bidder shall provide the redundant switched optical Ethernet communication infrastructure for SAS. One switch shall be provided to connect all IEDs in one diameter of each 765 and 400kV yard and for two bays of 220kV yard to communication infrastructure. Each switch shall have at least two spare ports for connecting bay level IEDs and one spare port for connecting station bus.

4.2 Bay level unit

The bay unit shall use industrial grade components. The bay level unit, based on microprocessor technology, shall use numerical techniques for the calculation and evaluation of externally input analogue signals. They shall incorporate select-before-operate control principles as safety measures for operation via the HMI. They shall perform all bay related functions, such as control commands, bay interlocking, data acquisition, data storage, event recording and shall provide inputs for status indication and outputs for commands. They shall be directly connected to the switchgear. The bay unit shall acquire and process all data for the bay (Equipment status, fault indications, measured values, alarms etc.) and transmit these to the other devices in sub-station automation system. In addition, this shall receive the operation commands from station HMI and control centre. The bay unit shall have the capability to store all the data for at least 24 hours.

One no. Bay level unit shall be provided for supervision and control of each 765, 400 and 220 kV bay (a bay comprises of one circuit breaker and associated disconnector, earth switches and instrument transformer). The Bay level unit shall be equipped with analogue and binary inputs/outputs for handling the control, status monitoring and analogue measurement functions. All bay level interlocks are to be incorporated in the Bay level unit so as to permit control from the Bay level unit/ local bay mimic panel, with all bay interlocks in place, during maintenance and commissioning or in case of contingencies when the Station HMI is out of service.

The bay control unit to be provided for the bays shall be preferably installed in the CB relay panel/feeder protection panel for respective bay. Further in case of one and half breaker schemes, the BCU for Tie CB shall be provided in Tie CB relay panel. The tie CB relay panel shall also house the Ethernet switch(es) to be provided for the diameter. The bay control unit for future bay (if required as per section project) shall be installed in a separate panel.

The Bay level unit shall meet the requirements for withstanding electromagnetic interference according to relevant parts of IEC 61850. Failure of any single component within the equipment shall neither cause unwanted operation nor lead to a complete system breakdown.

4.2.1 Input/Output (I/O) modules

The I/O modules shall form a part of the bay level unit and shall provide coupling to the substation equipment. The I/O modules shall acquire all switchgear information (i.e. data coming directly from the switchgear or from switchgear interlocking devices) and transmit commands for operation of the switchgear. The measured values of voltage and current shall be from the secondaries of instrument transformers. The digital inputs shall be acquired by exception with 1 ms resolution. Contact bouncing in digital inputs shall not be assumed as change of state

4.3 Switchyard Panel Room:

The **switchyard panel room shall be constructed to house** Bay level units, bay mimic, relay and protection panels, PLCC panels etc. one each for a diameter in 765/400kV sub-station and for two bays in 220kV Level. In case of incomplete diameter the switchyard panel room shall have necessary space for accommodating the future bay IEDs. The layout of equipment/panel shall be subject to Owner's approval. The switchyard panel room shall be provided with necessary illuminations, fire alarm system with at least two detectors **with necessary power supply if required** and it shall be wired to SAS. The detailed **constructional requirement of switchyard panel room is detailed in section civil of technical specification and air conditioning requirement of switchyard panel room shall be as detailed in section Air conditioning system of technical specification**. The air conditioner provided in switchyard panel room shall be monitored from substation automation system.

4.4 Extendibility in future

Offered substation automation system shall be suitable for extension in future for additional bays. During such requirement, all the drawings and configurations, alarm/event list etc. displayed shall be designed in such a manner that its extension shall be easily performed by the employer.

During such event, normal operation of the existing substation shall be unaffected and system shall not require a shutdown. The contractor shall provide all necessary software tools along with source codes to perform addition of bays in future and complete integration with SAS by the user. These software tools shall be able to configure IED, add additional analogue variable, alarm list, event list, modify interlocking logics etc. for additional bays/equipment which shall be added in future.

5.0 Software structure

The software package shall be structured according to the SAS architecture and strictly divided in various levels. Necessary firewall shall be provided at suitable points in software to protect the system. An extension of the station shall be possible with lowest possible efforts. Maintenance, modification or an extension of components of any feeder may not force a shut-down of the parts of the system which are not affected by the system adaptation.

5.1.1 Station level software

5.1.1.1 Human-machine interface (HMI)

The base HMI software package for the operator station shall include the main SAS functions and it shall be independent of project specific hardware version and operating system. It shall further include tools for picture editing, engineering and system configuration. The system shall be easy to use, to maintain, and to adapt according to specific user requirements. Systems shall contain a library with standard functions and applications.

5.1.2 Bay level software

5.1.1.1 System software

The system software shall be structured in various levels. This software shall be placed in a non-volatile memory. The lowest level shall assure system performance and contain basic functions, which shall not be accessible by the application and maintenance engineer for modifications. The system shall support the generation of typical control macros and a process database for user specific data storage. In case of restoration of links after failure, the software along with hardware shall be capable of automatically synchronising with the remaining system without any manual interface. This shall be demonstrated by contractor during integrated system test.

5.1.1.2 Application software

In order to ensure robust quality and reliable software functions, the main part of the application software shall consist of standard software modules built as functional block elements. The functional blocks shall be documented and thoroughly tested. They form part of a library. The application software within the control/protection devices shall be programmed in a functional block language.

5.1.1.3 Network Management System:

The contractor shall provide a network management system software for following management functions:

- a. Configuration Management
- b. Fault Management
- c. Performance Monitoring

This system shall be used for management of communication devices and other IEDs in the system. This NMS can be loaded in DR workstation and shall be easy to use, user friendly and menu based. The NMS shall monitor all the devices in the SAS and report if there is any fault in the monitored devices. The NMS shall

- (a) Maintain performance, resource usage, and error statistics for all managed links and devices and present this information via displays, periodic reports and on demand reports.
- (b) Maintain a graphical display of SAS connectivity and device status.
- (c) Issue alarms when error conditions occurs
- (d) Provide facility to add and delete addresses and links

5.1.1.4 The contractor shall provide each software in two copies in CD to load into the system in case of any problem related with Hardware/Communication etc.

6.0 TESTS

The substation automation system offered by the bidder shall be subjected to following tests to establish compliance with IEC 61850 for EHV sub-station equipment installed in sheltered area in the outdoor switchyard and specified ambient conditions:

6.1 Type Tests:

6.1.1 Control IEDs and Communication Equipment:

- a. **Power Input:**
 - i. Auxiliary Voltage
 - ii. Current Circuits
 - iii. Voltage Circuits
 - iv. Indications
- b. **Accuracy Tests:**
 - i. Operational Measurd Values
 - ii. Currents
 - iii. Voltages
 - iv. Time resolution
- c. **Insulation Tests:**
 - i. Dielectric Tests
 - ii. Impulse Voltage withstand Test
- d. **Influencing Quantities**

- i. Limits of operation
 - ii. Permissible ripples
 - iii. Interruption of input voltage
- e. Electromagnetic Compatibility Test:**
 - i. 1 MHZ. burst disturbance test
 - ii. Electrostatic Discharge Test
 - iii. Radiated Electromagnetic Field Disturbance Test
 - iv. Electrical Fast transient Disturbance Test
 - v. Conducted Disturbances Tests induced by Radio Frequency Field
 - vi. Magnetic Field Test
 - vii. Emission (Radio interference level) Test.
 - viii. Conducted Interference Test
- f. Function Tests:**
 - i. Indication
 - ii. Commands
 - iii. Measured value Acquisition
 - iv. Display Indications
- g. Environmental tests:**
 - i. Cold Temperature
 - ii. Dry Heat
 - iii. Wet heat
 - iv. Humidity (Damp heat Cycle)
 - v. Vibration
 - vi. Bump
 - vii. Shock

6.2 Factory Acceptance Tests:

The supplier shall submit a test specification for factory acceptance test (FAT) and commissioning tests of the station automation system for approval. For the individual bay level IED's applicable type test certificates shall be submitted.

The manufacturing and configuration phase of the SAS shall be concluded by the factory acceptance test (FAT). The purpose is to ensure that the Contractor has interpreted the specified requirements correctly and that the FAT includes checking to the degree required by the user. The general philosophy shall be to deliver a system to site only after it has been thoroughly tested and its specified performance has been verified, as far as site conditions can be simulated in a test lab. During FAT the entire Sub-station Automation System including complete control and protection system to be supplied under present scope shall be tested for complete functionality and configuration in factory itself. The extensive testing shall be carried out during FAT. The purpose of Factory Acceptance Testing is to ensure trouble free installation at site. No major configuration setting of system is envisaged at site.

If the complete system consists of parts from various suppliers or some parts are already installed on site, the FAT shall be limited to sub-system tests. In such a case, the complete system test shall be performed on site

together with the site acceptance test (SAT).

6.2.1 Hardware Integration Tests:

The hardware integration test shall be performed on the specified systems to be used for Factory tests when the hardware has been installed in the factory. The operation of each item shall be verified as an integral part of system. Applicable hardware diagnostics shall be used to verify that each hardware component is completely operational and assembled into a configuration capable of supporting software integration and factory testing of the system. The equipment expansion capability shall also be verified during the hardware integration tests. The vendor specifically demonstrates how to add a device in future in SAS during FAT. The device shall be from a different manufacturer than the SAS supplier.

6.2.2 Integrated System Tests:

Integrated system tests shall verify the stability of the hardware and the software. During the tests all functions shall run concurrently and all equipment shall operate a continuous 100 Hours period. The integrated system test shall ensure the SAS is free of improper interactions between software and hardware while the system is operating as a whole.

6.3 Site Acceptance Tests:

The site acceptance tests (SAT) shall completely verify all the features of SAS hardware and software. The bidder shall submit the detailed SAT procedure and SAT procedure shall be read in conjunction with the specification.

7.0 SYSTEM OPERATION

7.1 Substation Operation

7.1.1 NORMAL OPERATION

Operation of the system by the operator from the remote RCC or at the substation shall take place via industry standard HMI(Human Machine interface) subsystem consisting of graphic colour VDU , a standard keyboard and a cursor positioning device (mouse).

The coloured screen shall be divided into 3 fields :

- i) Message field with display of present time and date
- ii) Display field for single line diagrams
- iii) Navigation bar with alarm/condition indication

For display of alarm annunciation, lists of events etc a separate HMI View node. shall be provided.

All operations shall be performed with mouse and/or a minimum number of function keys and cursor keys. The function keys shall have different meanings depending on the operation. The operator shall see the relevant meanings as function tests displayed in the command field (i.e. operator prompting). For control actions, the switchgear (i.e. circuit breaker etc.) requested shall be selectable on the display by means of the cursor keys. The switching element selected shall then appear on the background that shall be flashing in a different color. The operator prompting shall distinguish between:-

- Prompting of indications e.g. fault indications in the switchgear, and
- prompting of operational sequences e.g. execution of switching operations

The summary information displayed in the message field shall give a rapid display of alarm/message of the system in which a fault has occurred and alarm annunciation lists in which the fault is described more fully.

Each operational sequence shall be divided into single operation steps which are initiated by means of the function keys/WINDOW command by mouse. Operator prompting shall be designed in such a manner that only the permissible keys are available in the command field related to the specific operation step. Only those switching elements shall be accessed for which control actions are possible. If the operation step is rejected by the system, the operator prompting shall be supported by additional comments in the message field. The operation status shall be reset to the corresponding preceding step in the operation sequence by pressing one of the function keys. All operations shall be verified. Incorrect operations shall be indicated by comments in the message field and must not be executed.

The offer shall include a comprehensive description of the system. The above operation shall also be possible via WINDOWS based system by mouse.

8.0 POWER SUPPLY

Power for the substation automation system shall be derived from substation 220V DC system.

Inverter of suitable capacity shall be provided for station HMI **disturbance recorder evaluation unit** and its peripheral devices e.g. printer etc. In the event of Power failure, necessary safeguard software shall be built for proper shutdown.

9.0 DOCUMENTATION

The following documents shall be submitted for employer's approval during detailed engineering:

- (a) System Architecture Drawing
- (b) Hardware Specification
- (c) Functional Design Document

- (d) Clear procedure describing how to add an IED/bay/diameter in future covering all major supplier

The following documentation to be provided for the system in the course of the project shall be consistent, CAD supported, and of similar look/feel. All CAD drawings to be provide in “dxf” format.

- List of Drawings
- Substation automation system architecture
- Block Diagram
- Guaranteed technical parameters, Functional Design Specification and Guaranteed availability and reliability
- Calculation for power supply dimensioning
- I/O Signal lists
- Schematic diagrams
- List of Apparatus
- List of Labels
- Logic Diagram (hardware & software)
- **Switchyard Panel Room** layout drawing
- Control Room Lay-out
- Test Specification for Factory Acceptance Test (FAT)
- Product Manuals
- Assembly Drawing
- Operator’s Manual
- Complete documentation of implemented protocols between various elements
- Listing of software and loadable in CD ROM
- Other documents as may be required during detailed engineering

Two sets of hard copy and Four sets of CD ROM containing all the as built documents/drawings shall be provided.

10.0 TRAINING, SUPPORT SERVICES, MAINTENANCE AND SPARES

10.1 Training

Contractor personnel who are experienced instructors and who speak understandable English shall conduct training. The contractor shall arrange on its own cost all hardware training platform required for successful training and understanding in India. The Contractor shall provide all necessary training material. Each trainee shall receive individual copies of all technical manuals and all other documents used for training. These materials shall be sent to Employer at least two months before the scheduled commencement of the particular training course. Class materials, including the documents sent before the training courses as well as class handouts, shall become the property of Employer. Employer reserves the right to copy such materials, but for in-house training and use only. Hands-on training shall utilize equipment identical to

that being supplied to Employer.

For all training courses, the travel (e.g., airfare) and per-diem expenses will be borne by the participants.

The Contractor shall quote training prices as indicated in BPS.

The schedule, location, and detailed contents of each course will be finalized during Employer and Contractor discussions.

10.2 Computer System Hardware Course

A computer system hardware course shall be offered, but at the system level only. The training course shall be designed to give Employer hardware personnel sufficient knowledge of the overall design and operation of the system so that they can correct obvious problems, configure the hardware, perform preventive maintenance, run diagnostic programs, and communicate with contract maintenance personnel. The following subjects shall be covered:

- (a) System Hardware Overview: Configuration of the system hardware.
- (b) Equipment Maintenance: Basic theory of operation, maintenance techniques and diagnostic procedures for each element of the computer system, e.g., processors, auxiliary memories, LANs, routers and printers. Configuration of all the hardware equipments.
- (c) System Expansion: Techniques and procedures to expand and add equipment such as loggers, monitors, and communication channels.
- (d) System Maintenance: Theory of operation and maintenance of the redundant hardware configuration, failover hardware, configuration control panels, and failover switches. Maintenance of protective devices and power supplies.
- (e) Subsystem Maintenance: Theory of design and operation, maintenance techniques and practices, diagnostic procedures, and (where applicable) expansion techniques and procedures. Classes shall include hands-on training for the specific subsystems that are part of Employer's equipment or part of similarly designed and configured subsystems. All interfaces to the computing equipment shall be taught in detail.
- (f) Operational Training: Practical training on preventive and corrective maintenance of all equipment, including use of special tools and instruments. This training shall be provided on Employer equipment, or on similarly configured systems.

10.3 Computer System Software Course

The Contractor shall provide a computer system software course that covers the following subjects:

- (a) System Programming: Including all applicable programming languages and all stand-alone service and utility packages provided

- with the system. An introduction to software architecture, Effect of tuning parameters (OS software, Network software, database software etc.) on the performance of the system.
- (b) Operating System: Including the user aspects of the operating system, such as program loading and integrating procedures; scheduling, management, service, and utility functions; and system expansion techniques and procedures
 - (c) System Initialization and Failover: Including design, theory of operation, and practice
 - (d) Diagnostics: Including the execution of diagnostic procedures and the interpretation of diagnostic outputs,
 - (e) Software Documentation: Orientation in the organization and use of system software documentation.
 - (f) Hands-on Training: One week, with allocated computer time for trainee performance of unstructured exercises and with the course instructor available for assistance as necessary.

10.4 **Application Software Course**

The Contractor shall provide a comprehensive application software courses covering all applications including the database and display building course. The training shall include:

- (a) Overview: Block diagrams of the application software and data flows. Programming standards and program interface conventions.
- (b) Application Functions: Functional capabilities, design, and major algorithms. Associated maintenance and expansion techniques.
- (c) Software Development: Techniques and conventions to be used for the preparation and integration of new software functions.
- (d) Software Generation: Generation of application software from source code and associated software configuration control procedures.
- (e) Software Documentation: Orientation in the organization and use of functional and detailed design documentation and of programmer and user manuals.
- (f) Hands-on Training: One week, with allocated computer time for trainee performance of unstructured exercises and with the course instructor available for assistance as necessary.

10.5 **Requirement of training:**

The contractor shall provide training for POWERGRID personnel comprehensively covering following courses.

S. No.	Name of Course
1	Computer System Hardware
2	Computer System Software
3	Application Software

11.0 **Maintenance**

11.1 **Maintenance Responsibility during the Guaranteed Availability Period.**

During Guaranteed Availability Period, the Contractor shall take continual actions to ensure the guaranteed availability and shall make available all the necessary resources such as specialist personnel, spare parts, tools, test devices etc. for replacement or repair of all defective parts and shall have prime responsibility for keeping the system operational. **During guarantee period as specified in tender document, contractor shall arrange bi-monthly visit of their representative to site to review the performance of system and in case any defect/shortcoming etc. is observed during the period, the same shall be set right by the contractor within 15 days.**

12.0 **RELIABILITY AND AVAILABILITY**

The SAS shall be designed so that the failure of any single component, processor, or device shall not render the system unavailable. The SAS shall be designed to satisfy the very high demands for reliability and availability concerning:

- Mechanical and electrical design
- Security against electrical interference (EMI)
- High quality components and boards
- Modular, well-tested hardware
- Thoroughly developed and tested modular software
- Easy-to-understand programming language for application programming
- Detailed graphical documentation and application software
- Built-in supervision and diagnostic functions
- Security
 - Experience of security requirements
 - Process know-how
 - Select before execute at operation
 - Process status representation as double indications
- Distributed solution
- Independent units connected to the local area network
- Back-up functions
- Panel design appropriate to the harsh electrical environment and ambient conditions
- Panel grounding immune against transient ground potential rise

Outage terms

1) Outage

The state in which substation automation system or a unit of SAS is unavailable for Normal Operation as defined in the clause 7.1 due to an event directly related to the SAS or unit of SAS. In the event, the owner has taken any equipment/ system other than Sub-station Automation System for schedule/forced maintenance, the consequent outage to SAS shall not be considered as outage for the purpose of availability.

2) Actual outage duration (AOD)

The time elapsed in hours between the start and the end of an outage. The time shall be counted to the nearest 1/4th of an hour. Time less than 1/4th of an hour shall be counted as having duration of 1/4th of an hour.

3) Period Hours (PH)

The number of hours in the reporting period. In a full year the period hour are 8760h (8784h for a leap year).

4) Actual Outage hours (AOH)

The sum of actual outage duration within the reporting period

$$AOH = \sum AOD$$

5) Availability:

Each SAS shall have a total availability of 99.98 % i.e. the ratio of total time duration minus the actual outage duration to total time duration.

12.1 Guarantees Required

The availability for the complete SAS shall be guaranteed by the Contractor. Bidder shall include in their offer the detailed calculation for the availability. The contractor shall demonstrate their availability guaranteed by conducting the availability test on the total sub-station automation system as a whole after commissioning of total Sub-station Automation system. The test shall verify the reliability and integrity of all sub-systems. Under these conditions the test shall establish an overall availability of 99.98%. After the lapse of 1000 Hours of cumulative test time, test records shall be examined to determine the conformance with availability criterion. In case of any outage during the availability test, the contractor shall rectify the problem and after rectification, the 1000 Hours period start after such rectification. If test object has not been met the test shall continue until the specified availability is achieved.

The contractor has to establish the availability in a maximum period of three months from the date of commencement of the availability test.

After the satisfactory conclusion of test both contractor and employer shall mutually agree to the test results and if these results satisfy the availability criterion, the test is considered to be completed successfully. After that the system shall be taken over by the employer and then the guarantee period shall start.

13.0 Spares

13.1 Consumables:

All consumables such as paper, cartridges shall be supplied by the contractor till the SAS is taken over by the owner. .

13.2 Availability Spares:

In addition to mandatory spares as listed in section project for SAS, the bidder is required to list the spares, which may be required for ensuring the guaranteed availability during the guaranteed availability period. The final list of spares shall form part of scope of supply and accordingly the price thereof shall be quoted by the bidder and shall be considered in the evaluation of the bids. During the guaranteed availability period, the spare parts supplied by the Contractor shall be made available to the Contractor for usage subject to replenishment at the earliest. Thus, at the end of availability period the inventory of spares with the Employer shall be fully replenished by the Contractor. However, any additional spares required to meet the availability of the system (which are not a part of the above spares supplied by the Contractor) would have to be supplied immediately by the Contractor free of cost to the Employer.

14.0 LIST OF EQUIPMENTS

Quantity of equipments shall be decided by bidder in order to achieve guaranteed reliability and availability as declared by bidder.

- i) Station HMI
- ii) Redundant Station HMI (in Hot-stand by mode)
- iii) Bay level units along with bay mimic **as detailed in section Project.**
- iv) **Bay Level Unit for Auxiliary system (as per requirement)**
- v) Disturbance Recorder Work Station(Maintenance HMI)
- vi) Colour Laser Printer – 1 No. (For Reports & Disturbance records)
- vii) Dot matrix printers - (one each for Alarms and log sheets)
- viii) All interface equipment for gateway to RCC and RSCC
- ix) Communication infrastructure between Bay level units, Station HMI, Printers, gateways, redundant LAN etc. as required
- x) Remote workstation including HMI and along with one printer
- xi) **Modems as per requirement.**
- xii) Any other equipment as necessary.

List of Analogue and Digital Inputs

Basic Monitoring requirements are:

- Switchgear status indication
- Measurements (U, I, P, Q, f)
- Event
- Alarm
- Winding temperature of transformers & reactors
- ambient temperature
- Status and display of 415V LT system, 220V & 48V DC system
- Status of display of Fire protection system and Air conditioning system.
- Acquisition of all counters in PLCC panels through potential free contacts from PLCC or independently by counting the receive/send commands.
- Acquisition of alarm and fault record from protection relays
- Disturbance records
- Monitoring the state of batteries by displaying DC voltage, charging current and load current etc.
- Tap-position of Transformer

List of Inputs

The list of input for typical bays is as below:-

Analogue inputs

- | | | |
|------|-------------------------------------|-------------------------------------|
| i) | For line | |
| | Current | R phase
Y phase
B phase |
| | Voltage | R-Y phase
Y-B phase
B-R phase |
| ii) | For transformer/reactor | |
| | Current | R phase
Y phase
B phase |
| | WTI (for transformer and reactor) | |
| | Tap position (for transformer only) | |
| iii) | For TBC and bus coupler | |
| | Current | R phase
Y phase
B phase |

- iv) Common
 - a) Voltage for Bus-I, Bus-II and Transfer bus wherever applicable

Voltage	R-Y phase
	Y-B phase
	B-R phase
 - b) Frequency for Bus-I and Bus-II
 - c) Ambient temperature (switchyard)
 - d) Switchyard Panel Room Temperature.**
 - e) LT system**
 - i) Voltage R-Y, Y-B, B-R of Main Switch Board section-I
 - ii) Voltage R-Y, Y-B, B-R of Main Switch Board section-II
 - iii) Voltage R-Y, Y-B, B-R of Diesel Generator
 - iv) Current from LT transformer-I
 - v) Current from LT transformer-II
 - vi) Current from Diesel Generator
 - vii) Voltage of 220V DCDB-I
 - viii) Voltage of 220V DCDB-II
 - ix) Current from 220V Battery set-I
 - x) Current from 220V Battery set-II
 - xi) Current from 220V Battery charger-I
 - xii) Current from 220V Battery charger-II
 - xiii) Voltage of 48V DCDB-I
 - xiv) Voltage of 48V DCDB-II
 - xv) Current from 48V Battery set-I
 - xvi) Current from 48V Battery set-II
 - xvii) Current from 48V Battery charger-I
 - xviii) Current from 48V Battery charger-II

Digital Inputs

The list of input for various bays/SYSTEM is as follows:

1. Line bays
 - i) Status of each pole of CB.
 - ii) Status of Isolator, Earth switch
 - iii) CB trouble
 - iv) CB operation/closing lockout
 - v) Pole discrepancy optd
 - vi) Trip coil faulty
 - vii) LBB optd
 - viii) Bus bar protn trip relay optd
 - ix) Main bkr auto recloser operated
 - x) Tie/transfer auto recloser operated
 - xi) A/r lockout
 - xii) Tie/transfer bkr a/r lockout
 - xiii) Direct trip-I/II sent
 - xiv) Direct trip-I/II received
 - xv) Main I/II blocking
 - xvi) Main I/II-Inter trip send
 - xvii) Main I/II-Inter trip received
 - xviii) O/V STAGE – I operated
 - xix) O/V STAGE – II operated

xx)	FAULT LOCATOR FAULTY
xxi)	MAIN-I/II CVT FUSE FAIL
xxii)	MAIN-I PROTN TRIP
xxiii)	MAIN-II PROTN TRIP
xxiv)	MAIN-I PSB ALARM
xxv)	MAIN-I SOTF TRIP
xxvi)	MAIN-I R-PH TRIP
xxvii)	MAIN-I Y-PH TRIP
xxviii)	MAIN-I B-PH TRIP
xxix)	MAIN-I START
xxx)	MAIN-I/II Carrier aided trip
xxxi)	MAIN-I/II fault in reverse direction
xxxii)	MAIN-I/II ZONE-2 TRIP
xxxiii)	MAIN-I/II ZONE-3 TRIP
xxxiv)	MAIN-I/II weak end infeed optd
xxxv)	MAIN-II PSB alarm
xxxvi)	MAIN-II SOTF TRIP
xxxvii)	MAIN-II R-PH TRIP
xxxviii)	MAIN-II Y-PH TRIP
xxxix)	MAIN-II B-PH TRIP
xl)	MAIN-II start
xli)	MAIN-II aided trip
xlii)	MAIN-I/II fault in reverse direction
xliii)	Back-up o/c optd
xliv)	Back-up e/f optd
xlv)	220V DC-I/II source fail
xlvi)	SPEECH CHANNEL FAIL
xlvii)	PLCC Protection Channel-I FAIL
xlviii)	PLCC Protection Channel-II FAIL

2. Transformer bays

i)	Status of each pole of CB, Isolator, Earth switch
ii)	CB trouble
iii)	CB operation/closing lockout
iv)	Pole discrepancy optd
v)	Trip coil faulty
vi)	LBB optd
vii)	Bus bar protn trip relay optd
viii)	REF OPTD
ix)	DIF OPTD
x)	OVERFLUX ALARM (MV)
xi)	OVERFLUX TRIP (MV)
xii)	OVERFLUX ALARM (HV)
xiii)	OVERFLUX TRIP (HV)
xiv)	HV BUS CVT ½ FUSE FAIL
xv)	MV BUS CVT ½ FUSE FAIL
xvi)	OTI ALARM/TRIP
xvii)	PRD OPTD
xviii)	OVERLOAD ALARM
xix)	BUCHOLZ TRIP
xx)	BUCHOLZ ALARM
xxi)	OLTC BUCHOLZ ALARM
xxii)	OLTC BUCHOLZ TRIP

- xxiii) OIL LOW ALARM
- xxiv) back-up o/c (HV) optd
- xxv) back-up e/f (HV)optd
- xxvi) 220v DC-I/II source fail
- xxvii) TAP MISMATCH
- xxviii) GR-A PROTN OPTD
- xxix) GR-B PROTN OPTD
- xxx) back-up o/c (MV) optd
- xxxi) back-up e/f (MV)optd

3. Transformer bays

- i) Status of each pole of CB, Isolator, Earth switch
- ii) CB trouble
- iii) CB operation/closing lockout
- iv) Pole discrepancy optd
- v) Trip coil faulty
- vi) LBB optd
- vii) Bus bar protn trip relay optd
- viii) REF OPTD
- ix) DIF OPTD
- x) HV BUS CVT ½ FUSE FAIL
- xi) OTI ALARM/TRIP
- xii) PRD OPTD
- xiii) BUCHOLZ TRIP
- xiv) BUCHOLZ ALARM
- xv) OIL LOW ALARM
- xvi) Back-up impedance relay
- xvii) 220v DC-I/II source fail
- xviii) GR-A PROTN OPTD
- xix) GR-B PROTN OPTD

4. Line/Bus Reactor bays (as applicable):

- i) Status of each pole of CB, Isolator, Earth switch
- ii) CB trouble
- iii) CB operation/closing lockout
- iv) Pole discrepancy optd
- v) Trip coil faulty
- vi) LBB optd
- vii) Bus bar protn trip relay optd
- viii) REF OPTD
- ix) DIF OPTD
- x) Line/ BUS CVT ½ FUSE FAIL
- xi) OTI ALARM/TRIP
- xii) PRD OPTD
- xiii) BUCHOLZ TRIP
- xiv) BUCHOLZ ALARM
- xv) OIL LOW ALARM
- xvi) Back-up impedance relay
- xvii) 220V DC-I/II source fail
- xviii) GR-A PROTN OPTD
- xix) GR-B PROTN OPTD

5 Bus bar Protection

- i) Bus bar main-I trip
- ii) Bus bar main-II trip
- iii) Bus bar zone-I CT open
- iv) Bus bar zone-II CT open
- v) Bus transfer CT sup. Optd
- vi) Bus transfer bus bar protn optd
- vii) Bus protection relay fail

6. Auxiliary system

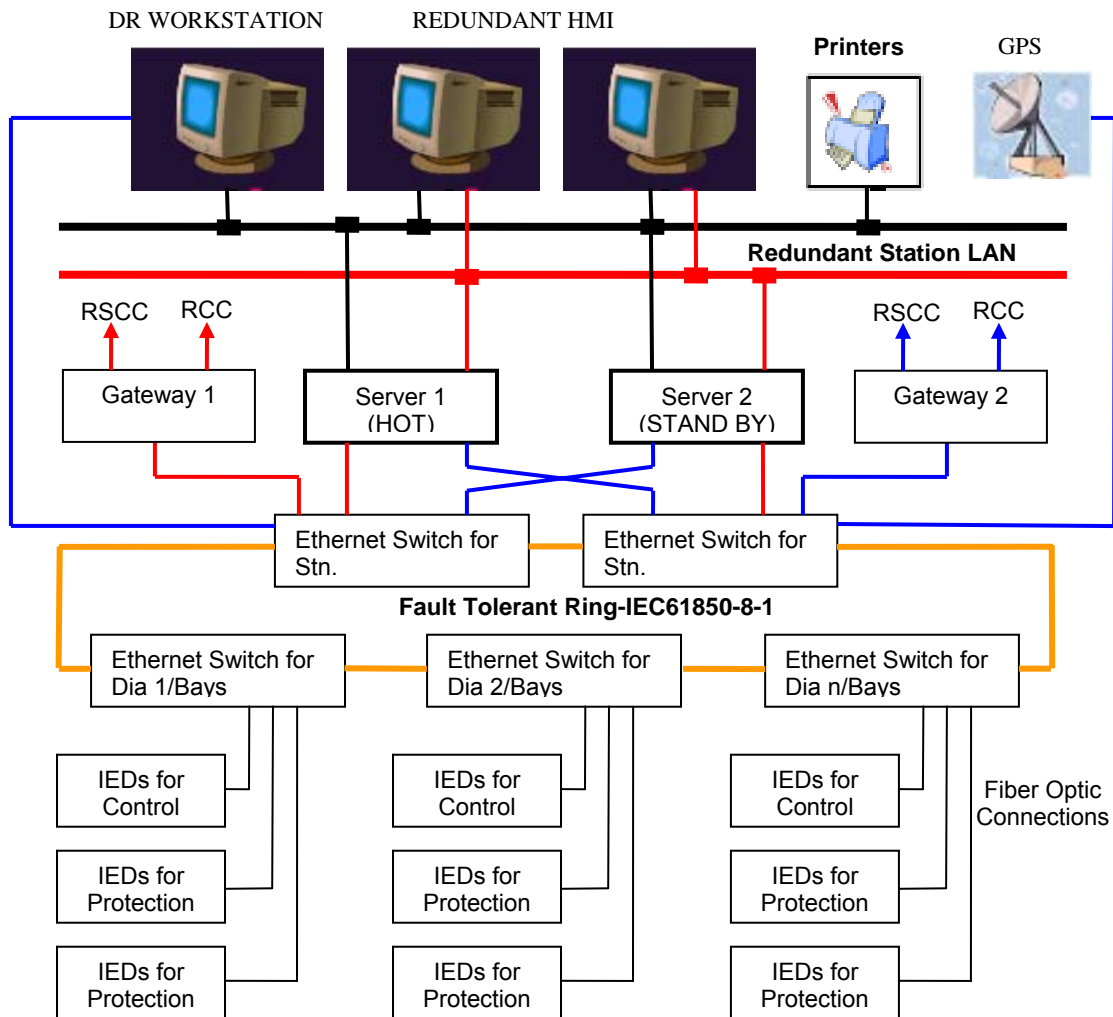
- i) Incomer-I On/Off
- ii) Incomer-II On/Off
- iii) 415V Bus-I/II U/V
- iv) 415v bus coupler breaker on/off
- v) DG set bkr on/off
- vi) Alarm/trip signals as listed in Section: DG set
- vii) LT transformer-I Buchholz Alarm & trip
- viii) LT transformer-II Buchholz Alarm & trip
- ix) LT transformer-I WTI Alarm & trip
- x) LT transformer-II WTI Alarm & trip
- xi) LT transformer-I OTI Alarm & trip
- xii) LT transformer-II OTI Alarm & trip
- xiii) PLCC exchange fail
- xiv) Time sync. Signal absent
- xv) Alarm/trip signals as listed in Section: Battery and Battery charger
- xvi) 220v DC-I earth fault
- xvii) 220v DC-II earth fault
- xviii) Alarm/trip signals as listed in Section: Fire protection system

7. Switchyard Panel Room:

- i) **AC Compressor 1 ON/OFF**
- ii) **AC Compressor 2 ON/OFF**
- iii) **Fire Detection 1 ON/OFF**
- iv) **Fire Detection 2 On/OFF**
- v) **Switchyard Panel Room Temperature High Alarm**

The exact number and description of digital inputs shall be as per detailed engineering requirement Apart from the above mentioned digital inputs, minimum of 200 inputs shall be kept for POWERGRID use in future.

TYPICAL ARCHITECTURAL DRAWING OF SUBSTATION AUTOMATION SYSTEM



Note:

1. The redundant managed bus shall be realized by high speed optical bus using industrial grade components and shall be as per IEC 61850.
2. The IEDs and switches for each of the dia. of 765kV and 400kV shall have separate switchyard panel room. For 220kV yards, IEDs for two bays can be housed in one switchyard panel room along with its switch.
3. Inside the sub-station, all connections shall be realized as per IEC 61850 protocol.
4. For gateway, it shall communicate with Remote Supervisory Control Centre (RSCC) on IEC 60870-5-101 protocol.
5. The printer as required shall be connected to station bus directly and can be managed either from station HMI, HMI view node or disturbance recorder work station.
6. The above layout is typical. However if any contractor offers slightly modified architecture based on their standard practice without compromising the working, the same shall be subject to approval during detailed engineering.



INTEROPERABILITY PROFILE OF IEC 60870-5-101 PROTOCOL FOR NR, NER AND ER

This companion standard presents sets of parameters and alternatives from which subsets have to be selected to implement particular telecontrol systems. Certain parameter values, such as the number of octets in the COMMON ADDRESS of ASDUs represent mutually exclusive alternatives. This means that only one value of the defined parameters is admitted per system. Other parameters, such as the listed set of different process information in command and in monitor direction allow the specification of the complete set or subsets, as appropriate for given applications. This clause summarizes the parameters of the previous clauses to facilitate a suitable selection for a specific application. If a system is composed of equipment stemming from different manufacturers it is necessary that all partners agree on the selected parameters.

The selected parameters should be marked in the white boxes as follows:

<input type="checkbox"/>	Function of ASDU is not used
<input checked="" type="checkbox"/>	Function or ASDU is used as standardized (default)

Note : In addition, the full specification of a system may require individual selection of certain parameters for certain parts of the system, such as the individual selection of scaling factors for individually addressable measured values.



1.1 SYSTEM OR DEVICE

(System-specific parameter, indicate the definition of a system or a device by marking one of the following with an '■')

- System definition
- Controlling station definition (master)
- Controlled station definition (Slave)

1.2 NETWORK CONFIGURATION

(Network-specific parameter, all configurations that are used are to be marked with)

- Point-to-point
- Multipoint-party line
- Multiple point-to-point
- Multipoint-star

1.3 PHYSICAL LAYER (Network-specific parameter)

Transmission speed (control direction) :

*Unbalanced interchange
circuit V.24/V.28
Standard*

*Unbalanced interchange
circuit V.24/V.28
Recommended if >1 200 bit/s*

*Balanced interchange
circuit X.24/X.27*

- | | | |
|---|---|---------------------------------------|
| <input type="checkbox"/> 100 bit/s | <input checked="" type="checkbox"/> 2 400 bit/s (ERLDC only) | <input type="checkbox"/> 2 400 bit/s |
| <input checked="" type="checkbox"/> 200 bit/s | <input type="checkbox"/> 4 800 bit/s | <input type="checkbox"/> 4 800 bit/s |
| <input checked="" type="checkbox"/> 300 bit/s | <input type="checkbox"/> 9 600 bit/s | <input type="checkbox"/> 9 600 bit/s |
| <input checked="" type="checkbox"/> 600 bit/s | | <input type="checkbox"/> 19 200 bit/s |
| <input checked="" type="checkbox"/> 1 200 bit/s | | <input type="checkbox"/> 38 400 bit/s |
| | | <input type="checkbox"/> 56 000 bit/s |
| | | <input type="checkbox"/> 64 000 bit/s |

(for unbalanced transmission only)

Transmission speed (monitor direction) :

*Unbalanced interchange
circuit V.24/V.28
Standard*

*Unbalanced interchange
circuit V.24/V.28
Recommended if >1 200 bit/s*

*Balanced interchange
circuit X.24/X.27*



<input type="checkbox"/>	100 bit/s	<input checked="" type="checkbox"/>	2 400 bit/s(ERLDC only)	<input type="checkbox"/>	2 400 bit/s
<input checked="" type="checkbox"/>	200 bit/s	<input type="checkbox"/>	4 800 bit/s	<input type="checkbox"/>	4 800 bit/s
<input checked="" type="checkbox"/>	300 bit/s	<input type="checkbox"/>	9 600 bit/s	<input type="checkbox"/>	9 600 bit/s
<input checked="" type="checkbox"/>	600 bit/s			<input type="checkbox"/>	19 200 bit/s
<input checked="" type="checkbox"/>	1 200 bit/s			<input type="checkbox"/>	38 400 bit/s
	<i>(for unbalanced transmission only)</i>			<input type="checkbox"/>	56 000 bit/s
				<input type="checkbox"/>	64 000 bit/s

1.4 LINK LAYER (*Network-specific parameter*)

Frame format FT 1.2, single character 1 and the fixed time out interval are used exclusively in this companion standard.

Link transmission procedure

- Balanced transmission
- Unbalanced transmission

Address field of the link

- Not present (balanced transmission only)
- One octet
- Two octets
- Structured
- Unstructured

Frame length

255 Maximum length L (number of octets)

1.5 APPLICATION LAYER

Transmission mode for application data

Mode 1 (Least significant octet first), as defined in clause 4.10 of IEC 870-5-4, is used exclusively in this companion standard.

Common address of ASDU

(system-specific parameter)

- One octet
- Two octets

Information object address

(system-specific parameter)



-
- | | |
|--|--|
| <input type="checkbox"/> One octet | <input type="checkbox"/> Structured |
| <input checked="" type="checkbox"/> Two octets | <input checked="" type="checkbox"/> Unstructured |
| <input type="checkbox"/> Three octets | |

Cause of transmission

(system-specific parameter)

- | | |
|---|---|
| <input checked="" type="checkbox"/> One octet | <input type="checkbox"/> Two octets (with originator address) |
|---|---|

Selection of standard ASDUs

(station-specific parameter)

- | | |
|--|-----------|
| <input checked="" type="checkbox"/> <1> := Single-point information | M_SP_NA_1 |
| <input checked="" type="checkbox"/> <2> := Single-point information with time tag | M_SP_TA_1 |
| <input checked="" type="checkbox"/> <3> := Double-point information | M_DP_NA_1 |
| <input checked="" type="checkbox"/> <4> := Double-point information with time tag | M_DP_TA_1 |
| <input type="checkbox"/> <5> := Step position information | M_ST_NA_1 |
| <input type="checkbox"/> <6> := Step position information with time tag | M_ST_TA_1 |
| <input type="checkbox"/> <7> := Bitstring of 32 bit | M_BO_NA_1 |
| <input type="checkbox"/> <8> := Bitstring of 32 bit with time tag | M_BO_TA_1 |
| <input checked="" type="checkbox"/> <9> := Measured value, normalized value | M_ME_NA_1 |
| <input type="checkbox"/> <10> := Measured value, normalized value with time tag | M_ME_TA_1 |
| <input checked="" type="checkbox"/> <11> := Measured value, scaled value | M_ME_NB_1 |
| <input type="checkbox"/> <12> := Measured value, scaled value with time tag | M_ME_TB_1 |
| <input type="checkbox"/> <13> := Measured value, short floating point value | M_ME_NC_1 |
| <input type="checkbox"/> <14> := Measured value, short floating point value with time tag | M_ME_TC_1 |
| <input checked="" type="checkbox"/> <15> := Integrated totals | M_IT_NA_1 |
| <input type="checkbox"/> <16> := Integrated totals with time tag | M_IT_TA_1 |
| <input type="checkbox"/> <17> := Event of protection equipment with time tag | M_EP_TA_1 |
| <input type="checkbox"/> <18> := Packed start events of protection equipment with time tag | M_EP_TB_1 |
| <input type="checkbox"/> <19> := Packed output circuit information of protection equipment with time tag | M_EP_TC_1 |
| <input type="checkbox"/> <20> := Packed single-point information with status change detection | M_PS_NA_1 |
| <input type="checkbox"/> <21> := Measured value, normalized value without quality descriptor | M_ME_ND_1 |

**Process information in control direction**

(station-specific parameter)

<input checked="" type="checkbox"/>	<45> :=	Single command	C_SC_NA_1
<input checked="" type="checkbox"/>	<46> :=	Double command	C_DC_NA_1
<input type="checkbox"/>	<47> :=	Regulating step command	C_RC_NA_1
<input type="checkbox"/>	<48> :=	Set point command, normalized value	C_SE_NA_1
<input checked="" type="checkbox"/>	<49> :=	Set point command, scaled value <small>(required only for analog output command)*</small>	C_SE_NB_1
<input type="checkbox"/>	<50> :=	Set point command, short floating point value	C_SE_NC_1
<input type="checkbox"/>	<51> :=	Bitstring of 32 bit	C_BO_NA_1

System information in monitor direction

(station-specific parameter)

<input checked="" type="checkbox"/>	<70> :=	End of initialization	M_EI_NA_1
-------------------------------------	---------	-----------------------	-----------

System information in control direction

(station-specific parameter)

<input checked="" type="checkbox"/>	<100> :=	Interrogation command	C_IC_NA_1
<input checked="" type="checkbox"/>	<101> :=	Counter interrogation command	C_CI_NA_1
<input type="checkbox"/>	<102> :=	Read command	C_RD_NA_1
<input checked="" type="checkbox"/>	<103> :=	Clock synchronization command <small>(optional, if GPS is used for time synch. of the RTU)*</small>	C_CS_NA_1
<input type="checkbox"/>	<104> :=	Test command	C_TS_NA_1
<input checked="" type="checkbox"/>	<105> :=	Reset process command	C_RP_NA_1
<input checked="" type="checkbox"/>	<106> :=	Delay acquisition command <small>(optional, if GPS is used for time synch. of the RTU)*</small>	C_CD_NA_1

Parameter in control direction

(station-specific parameter)

<input type="checkbox"/>	<110> :=	Parameter of measured value, normalized value	P_ME_NA_1
<input type="checkbox"/>	<111> :=	Parameter of measured value, scaled value	P_ME_NB_1
<input type="checkbox"/>	<112> :=	Parameter of measured value, short floating point value	P_ME_NC_1



<113> := Parameter activation P_AC_NA_1

File transfer (may not be required)*
(station-specific parameter)

- <120> := File ready F_FR_NA_1
- <121> := Section ready F_SR_NA_1
- <122> := Call directory, select file, call file, call section F_SC_NA_1
- <123> := Last section, last segment F_LS_NA_1
- <124> := Ack file, ack section F_AF_NA_1
- <125> := Segment F_SG_NA_1
- <126> := Directory F_DR_TA_1

Special use
(private range)

- <137> := Regulating delay command C_RC_NB_1
(for Raise/Lower command of OLTC .May not be required)*

1.6 BASIC APPLICATION FUNCTIONS

Station initialization
(station-specific parameter)

- Remote initialization

General interrogation
(system or station-specific parameter)

- Global
 - Group 1 ■ Group 7 ■ Group 13
 - Group 2 ■ Group 8 ■ Group 14
 - Group 3 ■ Group 9 ■ Group 15
 - Group 4 ■ Group 10 ■ Group 16
 - Group 5 ■ Group 11
 - Group 6 ■ Group 12
- Addresses per group have to be defined

Clock synchronization



(station-specific parameter)

- Clock synchronization (optional, if GPS is used for time synch. of the RTU)*

Command transmission (Required only when control command is envisaged)*
(object-specific parameter)

- Direct command transmission
- Direct set point command transmission
- No additional definition
- Short pulse duration (duration determined by a system parameter in the outstation)
- Long pulse duration (duration determined by a system parameter in the outstation)
- Persistent output
- Select and execute command
- Select and execute set point command
- C_SE ACTTERM used

Transmission of integrated totals
(station or object-specific parameter)

- Counter request
- Counter freeze without reset
- Counter freeze with reset
- Counter reset
- General request counter
- Request counter group 1
- Request counter group 2
- Request counter group 3
- Request counter group 4

Addresses per group have to be defined

Parameter loading
(object-specific parameter)

- Threshold value
- Smoothing factor
- Low limit for transmission of measured value
- High limit for transmission of measured value

Parameter activation
(object-specific parameter)

- Act/deact of persistent cyclic or periodic transmission of the addressed object



File transfer

(station-specific parameter)

- File transfer in monitor direction (for SOE data file from RTU to RLDC, may not be required)*
- File transfer in control direction (for downloading of RTU database from RLDC-May not be required)*



2. ADDITIONAL INFORMATION ON IEC 60870-5-101 FOR NRLDC, NERLDC AND ERLDC

A. Telemetry Data and ASDU mapping

The following table explains the type of the telemetered data and corresponding ASDUs used to transmit this data as per IEC 60870-5-101 protocol. These are same for all the above three RLDCs.

Type of Data	Data Unit type as per IEC	Description as per IEC	Data polling method	Interrogation group	Transmitted after Class-X request	Info Obj. Address range
Analog inputs (P,Q, V, f, OLTC tap position)	ASDU-11	Measured value scaled value	As cyclic data on Class 2 polls		Class 2	8448-
Digital inputs – Single status (Isolators, Protection signals) <small>A single status object uses the same IOA address when being sent as ASDU-1 or ASDU-2 or as a file transfer</small>	ASDU-1	Single point information	By exception (spontaneous) and on periodic Group scan	Group-1	Class 1 on exception, Class 1 after Group 1 scan	376-
	ASDU- 2	Single point information with time tag	By exception (spontaneous)		Class 1 on exception	376-
Digital inputs – Double status (Circuit breakers) <small>A double status object uses the same IOA address when being sent as ASDU-3 or ASDU-4 or as a file transfer</small>	ASDU-3	Double point information	By exception (spontaneous) and on periodic Group scan	Group-1	Class 1 on exception, Class 1 after Group 1 scan	256-
	ASDU-4	Double point information with time tag	By exception (spontaneous)		Class 1 on exception	256-
Pulse accumulators	ASDU-15	Integrated totals	By periodic counter interrogation	Group-1 (counter interrogation)	Class 2	12544-
Analog Outputs (Setpoint)	ASDU-48	Set point command Normalized value				37120
Digital Control command (CB Trip/Close)	ASDU 46	Double command				33024-
SOE (Digital inputs with Time)	File* transfer	See the file format enclosed				



B. DATA POLLING METHOD

1. The RTU shall respond to the Master stations request for the at least the following commands as per the protocol:
 - Status of Link
 - Reset of Link
 - Delay acquisition command *
 - Clock synchronization command *
 - General interrogation command
 - Interrogation of Scan group 1 command (all status data)
 - Interrogation of Scan group 2 command (all analog data)
 - Class 1/2 data polling
 - File transfer in Monitor direction (SOE file)*

If supervisory control commands are envisaged, then SBO procedure is to be used.
2. RTU shall send all Analog and status data in response to the General interrogation command.
3. All digital inputs are to be assigned to Scan group-1.
4. Analogs are defined as periodic data and are sent to RLDC on Class 2 request. The periodicity varies from 10 seconds to 15 seconds depending upon the quantity of data and available bandwidth.
5. Digital input state changes are to be reported spontaneously by RTU as Class 1 data. The Digital input data have higher priority than Analog values. An integrity scan is performed for all the digital inputs using Scan group-1 at every 10 minutes interval.
6. The SOE (Sequence of Events) information is stored in a file in the RTU. The format of SOE data is enclosed in a separate file (please see the details in *SOE_erldc_nerldc_nrldc.pdf* document). This file is transferred using the file transfer feature of IEC 60870-5-101 protocol.

* *These features may not be required*



INTEROPERABILITY PROFILE OF IEC 60870-5-101 PROTOCOL FOR SR

This companion standard presents sets of parameters and alternatives from which subsets have to be selected to implement particular telecontrol systems. Certain parameter values, such as the number of octets in the COMMON ADDRESS of ASDUs represent mutually exclusive alternatives. This means that only one value of the defined parameters is admitted per system. Other parameters, such as the listed set of different process information in command and in monitor direction allow the specification of the complete set or subsets, as appropriate for given applications. This clause summarizes the parameters of the previous clauses to facilitate a suitable selection for a specific application. If a system is composed of equipment stemming from different manufacturers it is necessary that all partners agree on the selected parameters.

The selected parameters should be marked in the white boxes as follows:

<input type="checkbox"/>	Function of ASDU is not used
<input checked="" type="checkbox"/>	Function or ASDU is used as standardized (default)

Note : In addition, the full specification of a system may require individual selection of certain parameters for certain parts of the system, such as the individual selection of scaling factors for individually addressable measured values.



1.1 SYSTEM or DEVICE

(System-specific parameter, indicate the definition of a system or a device by marking one of the following with an 'X')

- System definition
- Controlling station definition (master)
- Controlled station definition (Slave)

1.2 NETWORK CONFIGURATION

(Network-specific parameter, all configurations that are used are to be marked with)

- Point-to-point
- Multipoint-party line
- Multiple point-to-point
- Multipoint-star

1.3 PHYSICAL LAYER (Network-specific parameter)

Transmission speed (control direction) :

*Unbalanced interchange
circuit V.24/V.28
Standard*

*Unbalanced interchange
circuit V.24/V.28
Recommended if >1 200 bit/s*

*Balanced interchange
circuit X.24/X.27*

- | | | |
|---|--------------------------------------|---------------------------------------|
| <input type="checkbox"/> 100 bit/s | <input type="checkbox"/> 2 400 bit/s | <input type="checkbox"/> 2 400 bit/s |
| <input checked="" type="checkbox"/> 200 bit/s | <input type="checkbox"/> 4 800 bit/s | <input type="checkbox"/> 4 800 bit/s |
| <input checked="" type="checkbox"/> 300 bit/s | <input type="checkbox"/> 9 600 bit/s | <input type="checkbox"/> 9 600 bit/s |
| <input checked="" type="checkbox"/> 600 bit/s | | <input type="checkbox"/> 19 200 bit/s |
| <input checked="" type="checkbox"/> 1 200 bit/s | | <input type="checkbox"/> 38 400 bit/s |

(for unbalanced transmission only)

- | |
|---------------------------------------|
| <input type="checkbox"/> 56 000 bit/s |
| <input type="checkbox"/> 64 000 bit/s |

Transmission speed (monitor direction) :

*Unbalanced interchange
circuit V.24/V.28
Standard*

*Unbalanced interchange
circuit V.24/V.28
Recommended if >1 200 bit/s*

*Balanced interchange
circuit X.24/X.27*



-
- | | | | | | |
|-------------------------------------|---|--------------------------|-------------|--------------------------|--------------|
| <input type="checkbox"/> | 100 bit/s | <input type="checkbox"/> | 2 400 bit/s | <input type="checkbox"/> | 2 400 bit/s |
| <input checked="" type="checkbox"/> | 200 bit/s | <input type="checkbox"/> | 4 800 bit/s | <input type="checkbox"/> | 4 800 bit/s |
| <input checked="" type="checkbox"/> | 300 bit/s | <input type="checkbox"/> | 9 600 bit/s | <input type="checkbox"/> | 9 600 bit/s |
| <input checked="" type="checkbox"/> | 600 bit/s | | | <input type="checkbox"/> | 19 200 bit/s |
| <input checked="" type="checkbox"/> | 1 200 bit/s | | | <input type="checkbox"/> | 38 400 bit/s |
| | <i>(for unbalanced transmission only)</i> | | | <input type="checkbox"/> | 56 000 bit/s |
| | | | | <input type="checkbox"/> | 64 000 bit/s |

1.4 LINK LAYER (*Network-specific parameter*)

Frame format FT 1.2, single character 1 and the fixed time out interval are used exclusively in this companion standard.

Link transmission procedure

- Balanced transmission
- Unbalanced transmission

Address field of the link

- Not present (balanced transmission only)
- One octet
- Two octets
- Structured
- Unstructured

Frame length

255 Maximum length L (number of octets)

1.5 APPLICATION LAYER

Transmission mode for application data

Mode 1 (Least significant octet first), as defined in clause 4.10 of IEC 870-5-4, is used exclusively in this companion standard.

Common address of ASDU

(system-specific parameter)

- One octet
- Two octets

Information object address

(system-specific parameter)



- One octet Structured
 Two octets Unstructured
 Three octets

Cause of transmission

(system-specific parameter)

- One octet Two octets (with originator address)

Selection of standard ASDUs

(station-specific parameter)

- | | | |
|---|---|-----------|
| <input checked="" type="checkbox"/> <1> := | Single-point information | M_SP_NA_1 |
| <input checked="" type="checkbox"/> <2> := | Single-point information with time tag | M_SP_TA_1 |
| <input type="checkbox"/> <3> := | Double-point information | M_DP_NA_1 |
| <input type="checkbox"/> <4> := | Double-point information with time tag | M_DP_TA_1 |
| <input type="checkbox"/> <5> := | Step position information | M_ST_NA_1 |
| <input type="checkbox"/> <6> := | Step position information with time tag | M_ST_TA_1 |
| <input checked="" type="checkbox"/> <7> := | Bitstring of 32 bit | M_BO_NA_1 |
| <input type="checkbox"/> <8> := | Bitstring of 32 bit with time tag | M_BO_TA_1 |
| <input checked="" type="checkbox"/> <9> := | Measured value, normalized value | M_ME_NA_1 |
| <input type="checkbox"/> <10> := | Measured value, normalized value with time tag | M_ME_TA_1 |
| <input type="checkbox"/> <11> := | Measured value, scaled value | M_ME_NB_1 |
| <input type="checkbox"/> <12> := | Measured value, scaled value with time tag | M_ME_TB_1 |
| <input type="checkbox"/> <13> := | Measured value, short floating point value | M_ME_NC_1 |
| <input type="checkbox"/> <14> := | Measured value, short floating point value with time tag | M_ME_TC_1 |
| <input checked="" type="checkbox"/> <15> := | Integrated totals | M_IT_NA_1 |
| <input type="checkbox"/> <16> := | Integrated totals with time tag | M_IT_TA_1 |
| <input type="checkbox"/> <17> := | Event of protection equipment with time tag | M_EP_TA_1 |
| <input type="checkbox"/> <18> := | Packed start events of protection equipment with time tag | M_EP_TB_1 |
| <input type="checkbox"/> <19> := | Packed output circuit information of protection equipment with time tag | M_EP_TC_1 |



-
- | | | | |
|--------------------------|---------|--|-----------|
| <input type="checkbox"/> | <20> := | Packed single-point information with status change detection | M_PS_NA_1 |
| <input type="checkbox"/> | <21> := | Measured value, normalized value without quality descriptor | M_ME_ND_1 |

Process information in control direction

(station-specific parameter)

- | | | | |
|-------------------------------------|---------|---|-----------|
| <input checked="" type="checkbox"/> | <45> := | Single command | C_SC_NA_1 |
| <input type="checkbox"/> | <46> := | Double command | C_DC_NA_1 |
| <input type="checkbox"/> | <47> := | Regulating step command | C_RC_NA_1 |
| <input checked="" type="checkbox"/> | <48> := | Set point command, normalized value
(required only for analog output command)* | C_SE_NA_1 |
| <input type="checkbox"/> | <49> := | Set point command, scaled value | C_SE_NB_1 |
| <input type="checkbox"/> | <50> := | Set point command, short floating point value | C_SE_NC_1 |
| <input type="checkbox"/> | <51> := | Bitstring of 32 bit | C_BO_NA_1 |

System information in monitor direction

(station-specific parameter)

- | | | | |
|-------------------------------------|---------|-----------------------|-----------|
| <input checked="" type="checkbox"/> | <70> := | End of initialization | M_EI_NA_1 |
|-------------------------------------|---------|-----------------------|-----------|

System information in control direction

(station-specific parameter)

- | | | | |
|-------------------------------------|----------|---|-----------|
| <input checked="" type="checkbox"/> | <100> := | Interrogation command | C_IC_NA_1 |
| <input checked="" type="checkbox"/> | <101> := | Counter interrogation command | C_CI_NA_1 |
| <input type="checkbox"/> | <102> := | Read command | C_RD_NA_1 |
| <input checked="" type="checkbox"/> | <103> := | Clock synchronization command
(optional, if GPS is used for time synch. of the RTU)* | C_CS_NA_1 |
| <input type="checkbox"/> | <104> := | Test command | C_TS_NA_1 |
| <input type="checkbox"/> | <105> := | Reset process command | C_RP_NA_1 |
| <input checked="" type="checkbox"/> | <106> := | Delay acquisition command
(optional, if GPS is used for time synch. of the RTU)* | C_CD_NA_1 |

Parameter in control direction

(station-specific parameter)



<input type="checkbox"/> <110> :=	Parameter of measured value, normalized value	P_ME_NA_1
<input type="checkbox"/> <111> :=	Parameter of measured value, scaled value	P_ME_NB_1
<input type="checkbox"/> <112> :=	Parameter of measured value, short floating point value	P_ME_NC_1
<input type="checkbox"/> <113> :=	Parameter activation	P_AC_NA_1

File transfer (for downloading of database from RLDC, may not be required) *
(station-specific parameter)

<input checked="" type="checkbox"/> <120> :=	File ready	F_FR_NA_1
<input checked="" type="checkbox"/> <121> :=	Section ready	F_SR_NA_1
<input checked="" type="checkbox"/> <122> :=	Call directory, select file, call file, call section	F_SC_NA_1
<input checked="" type="checkbox"/> <123> :=	Last section, last segment	F_LS_NA_1
<input checked="" type="checkbox"/> <124> :=	Ack file, ack section	F_AF_NA_1
<input checked="" type="checkbox"/> <125> :=	Segment	F_SG_NA_1
<input type="checkbox"/> <126> :=	Directory	F_DR_TA_1

1.6 BASIC APPLICATION FUNCTIONS

Station initialization

(station-specific parameter)

- Remote initialization

General interrogation

(system or station-specific parameter)

- Global
 - Group 1
 - Group 2
 - Group 3
 - Group 4
 - Group 5
 - Group 6
 - Group 7
 - Group 8
 - Group 9
 - Group 10
 - Group 11
 - Group 12
 - Group 13
 - Group 14
 - Group 15
 - Group 16
- Addresses per group have to be defined

Clock synchronization



(station-specific parameter)

- Clock synchronization (optional, if GPS is used for time synch. of the RTU)*

Command transmission (Required only when control command is envisaged)*
(object-specific parameter)

- | | |
|--|--|
| <input checked="" type="checkbox"/> Direct command transmission | <input checked="" type="checkbox"/> Select and execute command |
| <input checked="" type="checkbox"/> Direct set point command transmission | <input checked="" type="checkbox"/> Select and execute set point |
| | <input type="checkbox"/> C_SE ACTTERM used |
| <input checked="" type="checkbox"/> No additional definition | |
| Short pulse duration (duration determined by a system parameter in the outstation) | |
| Long pulse duration (duration determined by a system parameter in the outstation) | |
| Persistent output | |

Transmission of integrated totals
(station or object-specific parameter)

- | | |
|--|--|
| <input checked="" type="checkbox"/> Counter request | <input type="checkbox"/> General request counter |
| <input checked="" type="checkbox"/> Counter freeze without reset | <input type="checkbox"/> Request counter group 1 |
| <input checked="" type="checkbox"/> Counter freeze with reset | <input type="checkbox"/> Request counter group 2 |
| <input type="checkbox"/> Counter reset | <input type="checkbox"/> Request counter group 3 |
| | <input type="checkbox"/> Request counter group 4 |

Addresses per group have to be defined

Parameter loading
(object-specific parameter)

- Threshold value
- Smoothing factor
- Low limit for transmission of measured value
- High limit for transmission of measured value

Parameter activation
(object-specific parameter)

- Act/deact of persistent cyclic or periodic transmission of the addressed object



File transfer

(station-specific parameter)

- File transfer in monitor direction
- File transfer in control direction (*For downloading of database from RLDC, May not be required*)*



2. ADDITIONAL INFORMATION ON IEC 60870-5-101 FOR SRLDC

A. Telemetred Data and ASDU mapping

The following table explains the type of the telemetred data and corresponding ASDUs used to transmit this data as per IEC 60870-5-101 protocol

Type of power system Data	Data Unit type as per IEC	Description as per IEC	Data polling method	Interr ogation group	Transmitted after Class-X request	Info Obj. Address range
Analog inputs (P,Q, V, f)	ASDU-9	Measured value normalized value	By periodic Group scan	Group-2	Class 2	2001-3000
Digital inputs –Single status (Circuit breakers, Isolators, Protection signals)	ASDU-1	Single point information	By exception (spontaneous) and on periodic Group scan	Group-1	Class 1 after exception, Class 2 after Group 1 scan	1-1000
	ASDU- 2 (for SOE)	Single point information with time tag	By exception (spontaneous)		Class 1 after exception	1001-2000
Pulse accumulators	ASDU-15	Integrated totals	By periodic counter interrogation	Group-1 (count er interro gation)	Class 2	4001-5000
Analog Outputs (Setpoint)	ASDU-48	Set point command Normalized value				5001-6000
Digital Control command (CB Trip/Close)	ASDU 45	Single command				3001-4000

B. DATA POLLING METHOD

- The RTU shall respond to the Master stations request for the at least the following commands as per the protocol:
 - Status of Link
 - Reset of Link
 - Delay acquisition command *
 - Clock synchronization command *
 - General interrogation command



- Interrogation of Scan group 1 command (all status data)
- Interrogation of Scan group 2 command (all analog data)
- Class 1/2 data polling

If supervisory control commands are envisaged, then SBO procedure is to be used.

2. Normal data polling is by Scan groups
3. All digital inputs are assigned to Scan group-1 and all Analog values are assigned to Scan group-2
4. Analog values are acquired periodically by using the Scan group-2 polling. This periodicity is ranging from 10-15 seconds based on the quantity of analogs and the communication channel bandwidth.
5. Digital input state changes are reported spontaneously by RTU as class 1 data and a integrity scan is performed for all the digital inputs using Scan group-1 at every 10 minutes interval.
6. Double bit digital status data are to be sent as two single-point information from the RTU.

** These features may not be required*



INTEROPERABILITY PROFILE OF IEC 60870-5-101 PROTOCOL FOR WR

This companion standard presents sets of parameters and alternatives from which subsets have to be selected to implement particular telecontrol systems. Certain parameter values, such as the number of octets in the COMMON ADDRESS of ASDUs represent mutually exclusive alternatives. This means that only one value of the defined parameters is admitted per system. Other parameters, such as the listed set of different process information in command and in monitor direction allow the specification of the complete set or subsets, as appropriate for given applications. This clause summarizes the parameters of the previous clauses to facilitate a suitable selection for a specific application. If a system is composed of equipment stemming from different manufacturers it is necessary that all partners agree on the selected parameters.

The selected parameters should be marked in the white boxes as follows:

<input type="checkbox"/>	Function of ASDU is not used
<input checked="" type="checkbox"/>	Function or ASDU is used as standardized (default)

Note : In addition, the full specification of a system may require individual selection of certain parameters for certain parts of the system, such as the individual selection of scaling factors for individually addressable measured values.



1.1 SYSTEM or DEVICE

(System-specific parameter, indicate the definition of a system or a device by marking one of the following with an 'X')

- System definition
- Controlling station definition (master)
- Controlled station definition (Slave)

1.2 NETWORK CONFIGURATION

(Network-specific parameter, all configurations that are used are to be marked with)

- Point-to-point
- Multipoint-party line
- Multiple point-to-point
- Multipoint-star

1.3 PHYSICAL LAYER (Network-specific parameter)

Transmission speed (control direction) :

*Unbalanced interchange
circuit V.24/V.28
Standard*

*Unbalanced interchange
circuit V.24/V.28
Recommended if >1 200 bit/s*

*Balanced interchange
circuit X.24/X.27*

- | | | |
|---|--------------------------------------|---------------------------------------|
| <input type="checkbox"/> 100 bit/s | <input type="checkbox"/> 2 400 bit/s | <input type="checkbox"/> 2 400 bit/s |
| <input type="checkbox"/> 200 bit/s | <input type="checkbox"/> 4 800 bit/s | <input type="checkbox"/> 4 800 bit/s |
| <input checked="" type="checkbox"/> 300 bit/s | <input type="checkbox"/> 9 600 bit/s | <input type="checkbox"/> 9 600 bit/s |
| <input checked="" type="checkbox"/> 600 bit/s | | <input type="checkbox"/> 19 200 bit/s |
| <input checked="" type="checkbox"/> 1 200 bit/s | | <input type="checkbox"/> 38 400 bit/s |

(for unbalanced transmission only)

- | |
|---------------------------------------|
| <input type="checkbox"/> 56 000 bit/s |
| <input type="checkbox"/> 64 000 bit/s |

Transmission speed (monitor direction) :

*Unbalanced interchange
circuit V.24/V.28
Standard*

*Unbalanced interchange
circuit V.24/V.28
Recommended if >1 200 bit/s*

*Balanced interchange
circuit X.24/X.27*



-
- | | | | | | |
|-------------------------------------|---|--------------------------|-------------|--------------------------|--------------|
| <input type="checkbox"/> | 100 bit/s | <input type="checkbox"/> | 2 400 bit/s | <input type="checkbox"/> | 2 400 bit/s |
| <input type="checkbox"/> | 200 bit/s | <input type="checkbox"/> | 4 800 bit/s | <input type="checkbox"/> | 4 800 bit/s |
| <input checked="" type="checkbox"/> | 300 bit/s | <input type="checkbox"/> | 9 600 bit/s | <input type="checkbox"/> | 9 600 bit/s |
| <input checked="" type="checkbox"/> | 600 bit/s | | | <input type="checkbox"/> | 19 200 bit/s |
| <input checked="" type="checkbox"/> | 1 200 bit/s | | | <input type="checkbox"/> | 38 400 bit/s |
| | <i>(for unbalanced transmission only)</i> | | | <input type="checkbox"/> | 56 000 bit/s |
| | | | | <input type="checkbox"/> | 64 000 bit/s |

1.4 LINK LAYER (*Network-specific parameter*)

Frame format FT 1.2, single character 1 and the fixed time out interval are used exclusively in this companion standard.

Link transmission procedure

- Balanced transmission
- Unbalanced transmission

Address field of the link

- Not present (balanced transmission only)
- One octet
- Two octets
- Structured
- Unstructured

Frame length

255 Maximum length L (number of octets)

1.5 APPLICATION LAYER

Transmission mode for application data

Mode 1 (Least significant octet first), as defined in clause 4.10 of IEC 870-5-4, is used exclusively in this companion standard.

Common address of ASDU

(system-specific parameter)

- One octet
- Two octets

Information object address

(system-specific parameter)



- One octet Structured
 Two octets Unstructured
 Three octets

Cause of transmission

(system-specific parameter)

- One octet Two octets (with originator address)

Selection of standard ASDUs

(station-specific parameter)

- | | | |
|---|---|-----------|
| <input checked="" type="checkbox"/> <1> := | Single-point information | M_SP_NA_1 |
| <input checked="" type="checkbox"/> <2> := | Single-point information with time tag | M_SP_TA_1 |
| <input checked="" type="checkbox"/> <3> := | Double-point information | M_DP_NA_1 |
| <input checked="" type="checkbox"/> <4> := | Double-point information with time tag | M_DP_TA_1 |
| <input type="checkbox"/> <5> := | Step position information | M_ST_NA_1 |
| <input type="checkbox"/> <6> := | Step position information with time tag | M_ST_TA_1 |
| <input checked="" type="checkbox"/> <7> := | Bitstring of 32 bit | M_BO_NA_1 |
| <input type="checkbox"/> <8> := | Bitstring of 32 bit with time tag | M_BO_TA_1 |
| <input checked="" type="checkbox"/> <9> := | Measured value, normalized value | M_ME_NA_1 |
| <input type="checkbox"/> <10> := | Measured value, normalized value with time tag | M_ME_TA_1 |
| <input type="checkbox"/> <11> := | Measured value, scaled value | M_ME_NB_1 |
| <input type="checkbox"/> <12> := | Measured value, scaled value with time tag | M_ME_TB_1 |
| <input type="checkbox"/> <13> := | Measured value, short floating point value | M_ME_NC_1 |
| <input type="checkbox"/> <14> := | Measured value, short floating point value with time tag | M_ME_TC_1 |
| <input checked="" type="checkbox"/> <15> := | Integrated totals | M_IT_NA_1 |
| <input type="checkbox"/> <16> := | Integrated totals with time tag | M_IT_TA_1 |
| <input type="checkbox"/> <17> := | Event of protection equipment with time tag | M_EP_TA_1 |
| <input type="checkbox"/> <18> := | Packed start events of protection equipment with time tag | M_EP_TB_1 |
| <input type="checkbox"/> <19> := | Packed output circuit information of protection equipment with time tag | M_EP_TC_1 |



-
- | | | | |
|--------------------------|---------|--|-----------|
| <input type="checkbox"/> | <20> := | Packed single-point information with status change detection | M_PS_NA_1 |
| <input type="checkbox"/> | <21> := | Measured value, normalized value without quality descriptor | M_ME_ND_1 |

Process information in control direction

(station-specific parameter)

- | | | | |
|-------------------------------------|---------|---|-----------|
| <input checked="" type="checkbox"/> | <45> := | Single command | C_SC_NA_1 |
| <input checked="" type="checkbox"/> | <46> := | Double command | C_DC_NA_1 |
| <input type="checkbox"/> | <47> := | Regulating step command | C_RC_NA_1 |
| <input checked="" type="checkbox"/> | <48> := | Set point command, normalized value
(required only for analog output command)* | C_SE_NA_1 |
| <input type="checkbox"/> | <49> := | Set point command, scaled value | C_SE_NB_1 |
| <input type="checkbox"/> | <50> := | Set point command, short floating point value | C_SE_NC_1 |
| <input type="checkbox"/> | <51> := | Bitstring of 32 bit | C_BO_NA_1 |

System information in monitor direction

(station-specific parameter)

- | | | | |
|-------------------------------------|---------|-----------------------|-----------|
| <input checked="" type="checkbox"/> | <70> := | End of initialization | M_EI_NA_1 |
|-------------------------------------|---------|-----------------------|-----------|

System information in control direction

(station-specific parameter)

- | | | | |
|-------------------------------------|----------|---|-----------|
| <input checked="" type="checkbox"/> | <100> := | Interrogation command | C_IC_NA_1 |
| <input checked="" type="checkbox"/> | <101> := | Counter interrogation command | C_CI_NA_1 |
| <input type="checkbox"/> | <102> := | Read command | C_RD_NA_1 |
| <input checked="" type="checkbox"/> | <103> := | Clock synchronization command
(optional, if GPS is used for time synch. of the RTU)* | C_CS_NA_1 |
| <input type="checkbox"/> | <104> := | Test command | C_TS_NA_1 |
| <input type="checkbox"/> | <105> := | Reset process command | C_RP_NA_1 |
| <input checked="" type="checkbox"/> | <106> := | Delay acquisition command
(optional, if GPS is used for time synch. of the RTU)* | C_CD_NA_1 |

Parameter in control direction

(station-specific parameter)



<input type="checkbox"/> <110> :=	Parameter of measured value, normalized value	P_ME_NA_1
<input type="checkbox"/> <111> :=	Parameter of measured value, scaled value	P_ME_NB_1
<input type="checkbox"/> <112> :=	Parameter of measured value, short floating point value	P_ME_NC_1
<input type="checkbox"/> <113> :=	Parameter activation	P_AC_NA_1

File transfer (for downloading of database from RLDC, may not be required)*
(station-specific parameter)

<input checked="" type="checkbox"/> <120> :=	File ready	F_FR_NA_1
<input checked="" type="checkbox"/> <121> :=	Section ready	F_SR_NA_1
<input checked="" type="checkbox"/> <122> :=	Call directory, select file, call file, call section	F_SC_NA_1
<input checked="" type="checkbox"/> <123> :=	Last section, last segment	F_LS_NA_1
<input checked="" type="checkbox"/> <124> :=	Ack file, ack section	F_AF_NA_1
<input checked="" type="checkbox"/> <125> :=	Segment	F_SG_NA_1
<input type="checkbox"/> <126> :=	Directory	F_DR_TA_1

1.6 BASIC APPLICATION FUNCTIONS

Station initialization

(station-specific parameter)

- Remote initialization

General interrogation

(system or station-specific parameter)

- Global
 - Group 1
 - Group 2
 - Group 3
 - Group 4
 - Group 5
 - Group 6
 - Group 7
 - Group 8
 - Group 9
 - Group 10
 - Group 11
 - Group 12
 - Group 13
 - Group 14
 - Group 15
 - Group 16
- Addresses per group have to be defined

Clock synchronization



(station-specific parameter)

- Clock synchronization (optional, if GPS is used for time synch. of the RTU)*

Command transmission (Required only when control command is envisaged)*
(object-specific parameter)

- | | |
|--|--|
| <input type="checkbox"/> Direct command transmission | <input checked="" type="checkbox"/> Select and execute command |
| <input type="checkbox"/> Direct set point command transmission | <input checked="" type="checkbox"/> Select and execute set point |
| | <input type="checkbox"/> C_SE ACTTERM used |
| <input checked="" type="checkbox"/> No additional definition | |
| Short pulse duration (duration determined by a system parameter in the outstation) | |
| Long pulse duration (duration determined by a system parameter in the outstation) | |
| Persistent output | |

Transmission of integrated totals
(station or object-specific parameter)

- | | |
|--|--|
| <input checked="" type="checkbox"/> Counter request | <input type="checkbox"/> General request counter |
| <input checked="" type="checkbox"/> Counter freeze without reset | <input type="checkbox"/> Request counter group 1 |
| <input checked="" type="checkbox"/> Counter freeze with reset | <input type="checkbox"/> Request counter group 2 |
| <input type="checkbox"/> Counter reset | <input type="checkbox"/> Request counter group 3 |
| | <input type="checkbox"/> Request counter group 4 |

Addresses per group have to be defined

Parameter loading
(object-specific parameter)

- Threshold value
- Smoothing factor
- Low limit for transmission of measured value
- High limit for transmission of measured value

Parameter activation
(object-specific parameter)

- Act/deact of persistent cyclic or periodic transmission of the addressed object



File transfer

(station-specific parameter)

- File transfer in monitor direction
- File transfer in control direction (*For downloading of database from RLDC, May not be required*)*



ADDITIONAL INFORMATION ON IEC 60870-5-101 FOR WRLDC

A. Telemetred Data and ASDU mapping

The following table explains the type of the telemetred data and corresponding ASDUs used to transmit this data as per IEC 60870-5-101 protocol

Type of power system Data	Data Unit type as per IEC	Description as per IEC	Data polling method	Scan group	Transmitted after Class-X request	Info Obj. Address range
Analog inputs (P,Q, V, f)	ASDU-9	Measured value normalized value	By periodic Group scan	Group-3	Class 2	3001-4000
Digital inputs – Single status (Isolators, Protection signals)	ASDU-1	Single point information	By exception (spontaneous) and on periodic Group scan	Group-1	Class 1 after exception, Class 1 after Group 1 scan	1-1000
	ASDU- 2 (for SOE)	Single point information with time tag	By exception (spontaneous)		Class 1 after exception	1001-2000
Digital inputs - Double status (Circuit breaker)	ASDU 3	Double point information	By exception (spontaneous) and on periodic Group scan	Group 2	Class 1 after exception, Class 1 after Group 1 scan	2001-3000
	ASDU-4	Double point information with time tag	By exception (spontaneous)		Class 1 after exception	Same address range as above
Pulse accumulators	ASDU-15	Integrated totals	By periodic counter interrogation	Group-1 (counter interrogation)	Class 2	5001-6000
Analog Outputs (Setpoint)	ASDU-48	Set point command Normalized value				6001-7000
Digital Control command (CB Trip/Close)	ASDU 45	Single command				4501-5000
Digital Control command (CB Trip/Close)	ASDU 46	Double command				4001-4500



B. DATA POLLING METHOD

1. The RTU shall respond to the Master stations request for the at least the following commands as per the protocol:
 - Status of Link
 - Reset of Link
 - Delay acquisition command *
 - Clock synchronization command *
 - General interrogation command
 - Interrogation of Scan group 1 command (all single status digital data)
 - Interrogation of Scan group 2 command (all double status digital data analog data)
 - Interrogation of Scan group 3 command (all analog data)
 - Class 1/2 data pollingIf supervisory control commands are envisaged, then SBO procedure is to be used.
2. Normal data polling is by Scan groups
3. All single digital inputs are assigned to Scan group-1, all double digital inputs are assigned to Scan group-2 and all Analog values are assigned to Scan group-3
4. Analog values are acquired periodically by using the Scan group-3 polling. This periodicity is ranging from 10-15 seconds based on the quantity of analogs and the communication channel bandwidth.
5. Digital input state changes are reported spontaneously by RTU as class 1 data and a integrity scan is performed for all the digital inputs using Scan group-1 and Scan group-2 at every 10 minutes interval.

** These features may not be required*

3 FUNCTIONAL SPECIFICATIONS

Appendix-I Part-IV

3.1 SOFTWARE EVOLUTIONS

3.1.1 RTU evolutions

3.1.1.1 Sequence of events (SOE)

The SOE data is time-oriented listings of status change events collected from RTUs. It is collected by the master station for subsequent review by relevant user personnel.

3.1.1.1.1 File structure

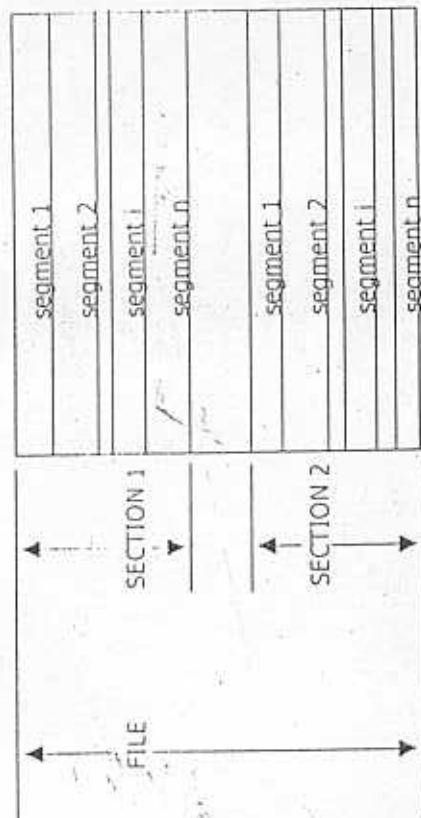


Figure 1. General construction of a file (in IEC 870-5-5)

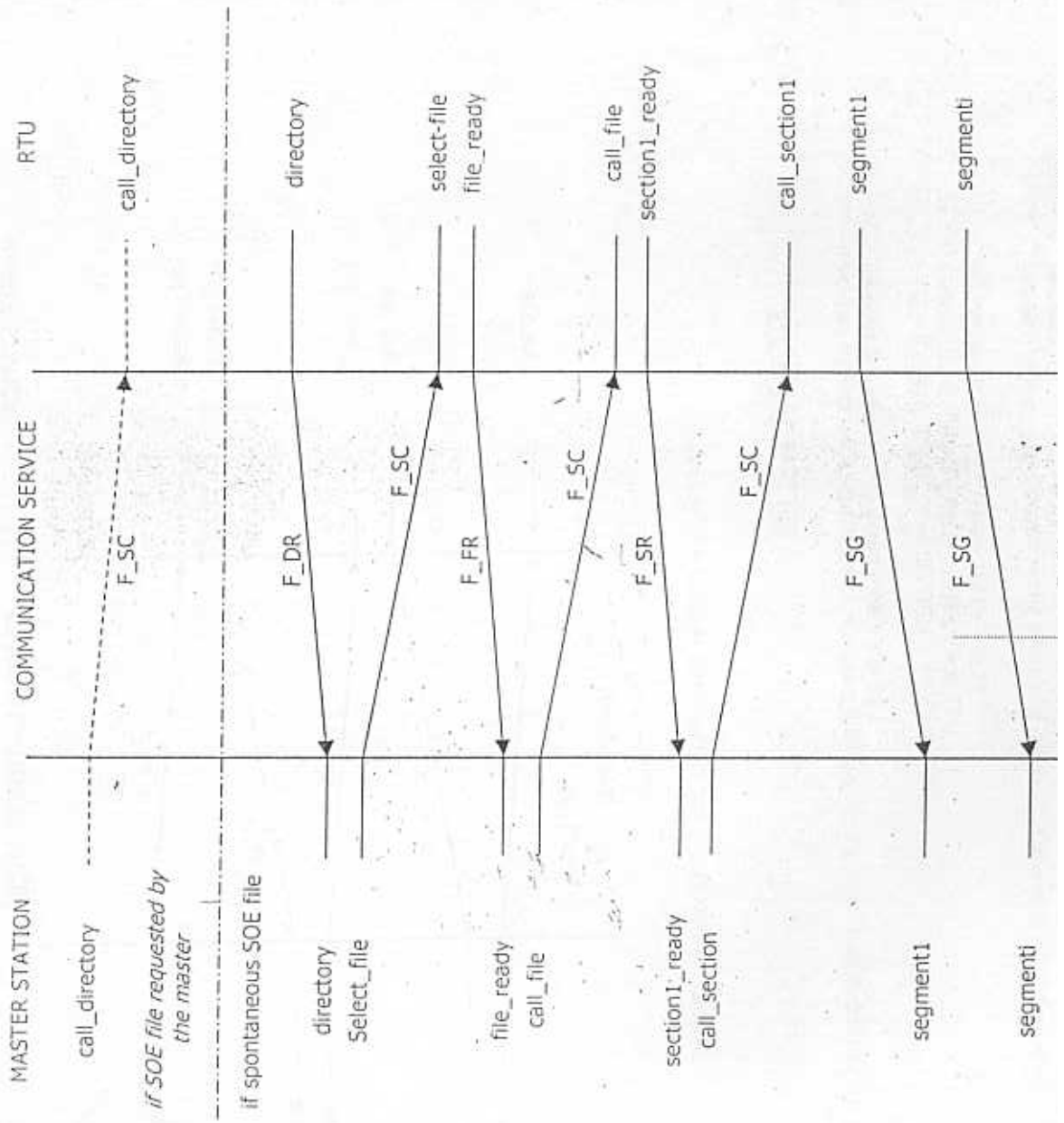
Special S900 case:

RTU S900 use one section to transfer file such database (to RTU) and SOE file (to control centre).



Figure 2. S900 File structure

For the SOE the file transfer procedure is used. The exchange of data is described in the IEC 870.5.5 document; chapter 6.12 and the message (ASDU) are described in the IEC 870.5.101 document, chap 7.3.6.



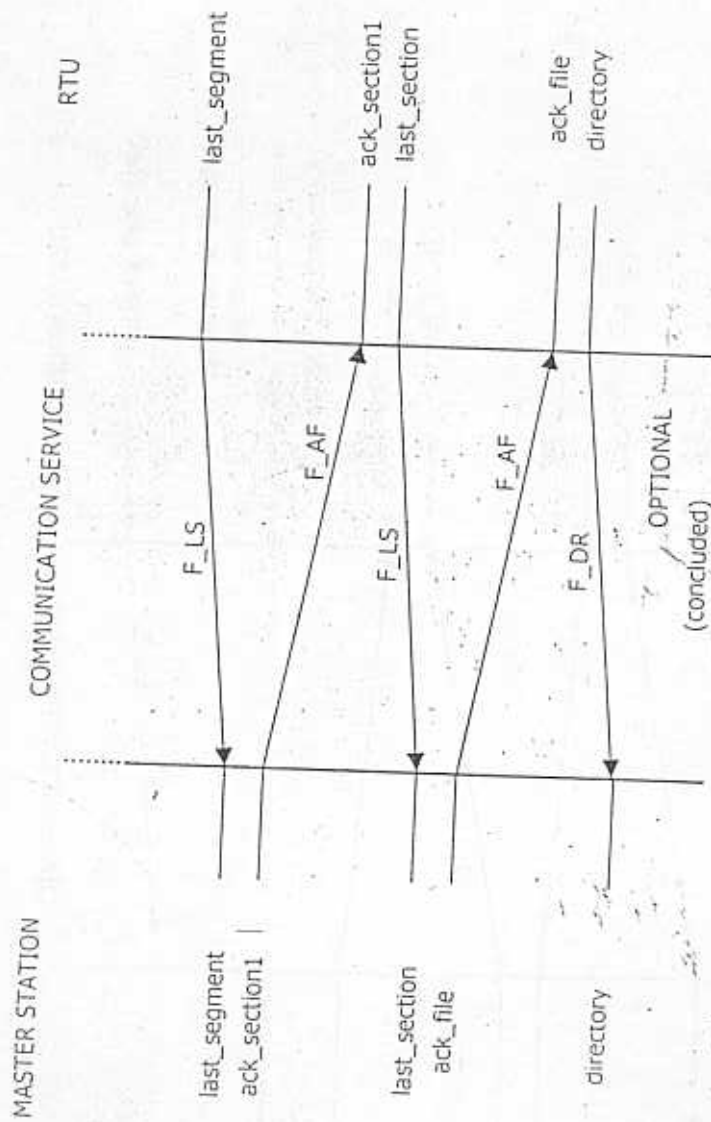


Figure 3. File transfer sequential procedure (monitor direction)

3.1.1.1.3 SOE file

For this project, we define a file by an identification part, a header part and an informational part. Each part has a length sub-part and a data sub-part.

FILE = IDENTIFICATION + HEADER + INFORMATION
 IDENTIFICATION = LENGTH + DATA + [FILL]
 INFORMATION = LENGTH + DATA + [FILL]

The field "LENGTH" is coded with 4 bytes and is rounded to a long word boundary.
 The field "DATA" is described on the next sub-section.

3.1.1.1.4 SOE structure

The file used for SOE has a capacity of 1200 events (1200 if one configured master station, 600 if two configured master station, 400 if three configured master station). If the RTU is not polled a long time, and if the SOE file is full, the oldest event is deleted and replaced by a RS with the address zero and the new one is stored into the SOE circular file.

Individual points can be configured for the SOE recording. It means that for these points, when an event occurs, a message M_SP_NA_1, M_SP_TA_1, M_DP_NA_1, M_DP_TA_1 (change of status for single or double point) is sent to the control centre and it is also stored in the SOE file. For the others, the RTU sends only the change of status to the control centre.

Each RS could be configured as SOE or not SOE. RS are transmitted with time tag or not (It depends on a global parameter of database). The SOE files are sent through class 2. As it is described in document R2, RS changes of state with timetag are sent by class 1 and without timetag are sent by class 2.

On normal condition, when the file is < parameter2 > % full, the RTU sends to the control centre the ASDU directory (F_DR_NA_1). Then the control centre could request the SOE file from the RTU. This % limit is a parameter of the system (ranging from 25% to 95%, 25% is the default value). RTU keeps the SOE file until the last message of the file transfer is acquitted; after all the parts of the file are transmitted, all SOE records sent are deleted from this file (without any loss of new SOE record event) after receive an ASDU F_AF_NA_1 (ack_file) acknowledging the file transfer (compliant with IEC 870.5.5). But if the SOE file is overflow, the last transfer in progress will be lost.

Note(s): < parameter1 >, < parameter2 > are configurable parameters and could be easily changed using S900/CETT configuration.

The IEC file name for the SOE file is 255 (00FF hexadecimal).

The SOE file could be requested by the control centre by sending a select file ASDU directly.

The SOE file is empty at the starting of the RTU.

The file transfer for SOE should be completely redundant. It means it is possible to swap the communication line without any perturbation on the file transfer procedure: after a change of path, the file transfer should be continue at the point where it was before the change of path.

3.1.1.1.5 Structure of the SOE file

FILE = IDENTIFICATION + HEADER + INFORMATION
IDENTIFICATION = LENGTH + DATA + [FILL]
INFORMATION = LENGTH + DATA + [FILL]

IDENTIFICATION = LENGTH + DATA + [FILL]
LENGTH = 40 (4bytes)
DATA = name + version
name = 'SEQUENCE OF EVENTS' (32 bytes)
version = version with UI8 format (1 byte)
[FILL] = 3 null bytes (3 bytes)

HEADER = LENGTH + DATA + [FILL]
LENGTH = 8 (4bytes)
DATA = number of SOE (2 bytes)
[FILL] = 2 null bytes (2 bytes)

INFORMATION = LENGTH + DATA + [FILL]
LENGTH = (10 * number of SOE) + 4, rounded to a longword boundary
DATA = set of ATOMIC SOE
ATOMIC-SOE = I/O address + status + time_stamp
I/O address = information object address (2 bytes)
status = SIQ or OIQ format (1 byte) with new SD flag
(0 = single/1 = double) on the BS1[4] Position.
time-stamp = CP56Time2a format (7 bytes)
[FILL] = 0 or 2 null bytes.

3.1.1.1 ATOMIC SOE structure

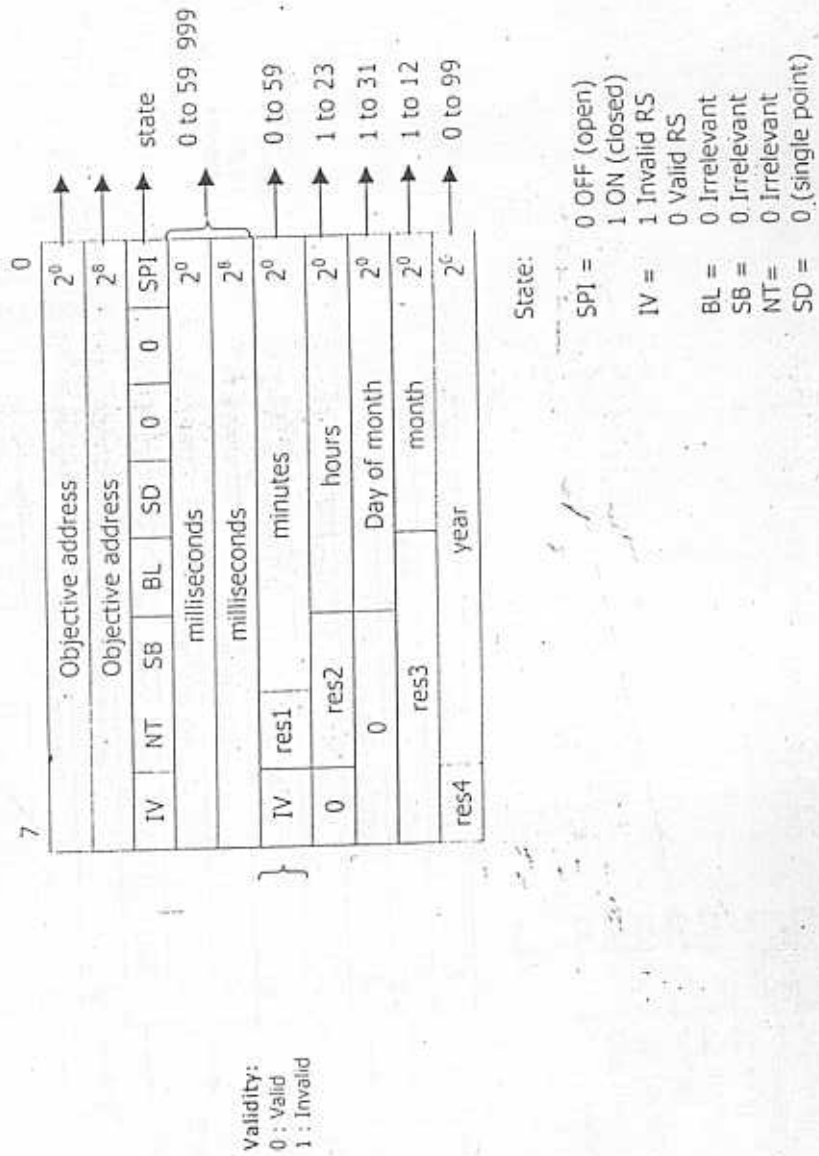
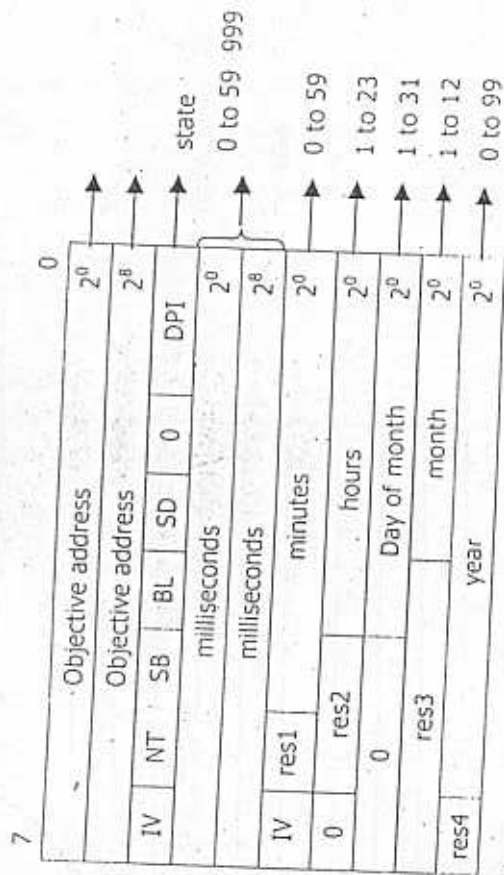


Figure 4. Atomic SOE (single point)



Validity:
 0 : Valid
 1 : Invalid

State:

DPI = 0 indeterminate state
 DPI = 1 OFF (open)
 DPI = 2 ON (closed)
 DPI = 3 invalid
 IV = 1 TS Invalid
 IV = 0 TS Valid
 BL = 0 Irrelevant
 SB = 0 Irrelevant
 NT = 0 Irrelevant
 SD = 0 (double point)

Figure 5. Atomic SOE (double point)

List of IO Points to be transmitted to RSCC

- a) MW and MVAR for all lines , transformers ,reactors and Capacitors
- b) Voltage of all buses
- c) Frequency of all 400Kv and 765kV Buses
- d) Frequency of one 220Kv Bus
- e) All Breakers
- f) All isolators
- g) Tap Position for all transformers
- h) Master protection signal for all feeders, transformers Units and Bus Bar
- i) Loss of Voltage signal for Bus bar
- j) All the points identified in point (e),(h) and (i) above as GPS Time stamped.
- k) Temperature value per substation.
- l) Any other point decided during detailed engineering